Hydro MPC

Service instructions







Hydro MPC

English (GB)	
Service instructions	 4

Original service instructions

Table of contents

1.	General information	
1.1 1.2	Hazard statements	
2.	Identification.	5
2.1	Nameplate	
2.2	Type key	
2.3	Identification, IO 351.	
2.4 2.5	Identification, CU 352	
3.	Technical data	8
3.1	Pressure	
3.2	Temperature.	
3.3 3.4	Relative humidity	
3.4 3.5	Electrical data.	
4. 4.1	CU 352 and IO 351	
4.1	Functions of terminals, IO 351A and IO 351B	
4.2.1	IO 351A	
	IO 351B	
	Overview of inputs and outputs of modules	
4.2.4	- , ,	
	Internal and external connections	11
4.2.6	CU 352 and IO 351 installation and operating instructions	27
5.	Fault correction tools	28
5.1	MPC/CU 352 indicator lights and alarm relay	
5.1		20
5.2	MPC display.	28
5.2 5.2.1	MPC display	28 28
5.2 5.2.1 5.2.2	MPC display	. 28 . 28 . 28
5.2 5.2.1 5.2.2 5.2.3	MPC display.	28 28 28 28 28 29
5.2 5.2.1 5.2.2 5.2.3 5.2.4	MPC display.	. 28 . 28 . 28 . 28 . 29 . 29
5.2 5.2.1 5.2.2 5.2.3	MPC display.	28 28 28 28 28 29 29 29 29 29 29
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4	MPC display.	28 28 28 28 29 29 29 29 29 29 20 29 20 20 20 20 20 20 20 20 20 20 20 20 20
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor	28 28 28 29 29 32 32 32 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration	28 28 29 29 32 32 32 32 32 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.3	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration Custom configuration	28 28 29 29 32 32 32 32 32 32 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration Custom configuration Data logging.	28 28 29 29 32 32 32 32 32 32 32 32 32 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.3 5.4.4 5.4.5 5.4.6	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration Custom configuration Data logging. Updating configuration files	28 28 29 29 32 32 32 32 32 32 32 32 32 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.3 5.4.4 5.4.5 5.4.6 6.	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC.	28 28 28 29 29 32 32 32 32 32 32 32 32 32 32 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.3 5.4.4 5.4.5 5.4.6 6.	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment	. 28 . 28 . 28 . 29 . 29 . 32 . 32 . 32 . 32 . 32 . 32 . 32 . 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.1 6.2	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC	28 28 29 29 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.1 6.2 6.2.1	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any	28 28 28 29 29 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.1 6.2 6.2.1 6.2.2	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC	28 28 28 29 29 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.1 6.2 6.2.1 6.2.2 6.2.3	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any Configuration of CU 352	28 28 28 29 29 32 33 35
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.1 6.2 6.2.1 6.2.2 6.2.3	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment. Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any Configuration of CU 352 Configuration of external frequency converters, if any	28 28 29 29 32 33 35 38
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.1 6.2 6.2.1 6.2.2 6.2.3 6.2.4	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment. Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any Configuration of CU 352 Configuration of external frequency converters, if any Step-by-step configuration of E-pumps, if any	28 28 28 29 29 32 33 33 35 38 39
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.2 6.2.1 6.2.2 6.2.3 6.2.4 7.	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any Configuration of CU 352 Configuration of external frequency converters, if any Step-by-step configuration of E-pumps, if any Danfoss frequency converters	. 28 . 28 . 28 . 29 . 29 . 32 . 32 . 32 . 32 . 32 . 32 . 32 . 32
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.2 6.2.1 6.2.2 6.2.3 6.2.4 7. 8.	MPC display. Status (1) Alarm log (3.2) Passwords. Alarm list. Grundfos GO PC Tool E-products Network list Monitor. Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any Configuration of CU 352 Configuration of external frequency converters, if any Step-by-step configuration of E-pumps, if any Danfoss frequency converters CUE. MGE Disposal.	28 28 28 29 29 32 33 35 38 39 39 39 39 39 39
5.2 5.2.1 5.2.2 5.2.3 5.2.4 5.3 5.4 5.4.1 5.4.2 5.4.3 5.4.4 5.4.5 5.4.6 6. 6.2 6.2.1 6.2.2 6.2.3 6.2.4 7. 8. 9.	MPC display. Status (1) Alarm log (3.2) Passwords Alarm list Grundfos GO PC Tool E-products Network list Monitor Standard configuration Custom configuration Data logging. Updating configuration files Configuration of Hydro MPC. Necessary equipment Factory configuration of Hydro MPC Setting the GENIbus number in IO 351 modules, if any Configuration of CU 352 Configuration of E-pumps, if any Step-by-step configuration of E-pumps, if any Step-by-step configuration of E-pumps, if any MGE	28 28 28 29 29 32 33 35 38 39 39 39 39 39 39 39 39 39

1. General information



Read this document before you start service work on the system. Service work must comply with local regulations and accepted codes of good practice. Observe the safety instructions in the installation and operating instructions for the system.

1.1 Hazard statements

The symbols and hazard statements below may appear in Grundfos installation and operating instructions, safety instructions and service instructions.



DANGER

Indicates a hazardous situation which, if not avoided, will result in death or serious personal injury.

WARNING

Indicates a hazardous situation which, if not avoided, could result in death or serious personal injury.



Indicates a hazardous situation which, if not avoided, could result in minor or moderate personal injury.

The hazard statements are structured in the following way:

SIGNAL WORD



Consequence of ignoring the warning

Action to avoid the hazard.

1.2 Notes

The symbols and notes below may appear in Grundfos installation and operating instructions, safety instructions and service instructions.



Observe these instructions for explosion-proof products.



A blue or grey circle with a white graphical symbol indicates that an action must be taken.



A red or grey circle with a diagonal bar, possibly with a black graphical symbol, indicates that an action must not be taken or must be stopped.



If these instructions are not observed, it may result in malfunction or damage to the equipment.



Tips and advice that make the work easier.

2. Identification

This section shows the nameplate, the type key and the codes that can appear in the variant code.



As codes can be combined, a code position may contain more than one code (letter).

2.1 Nameplate



Nameplate example

Pos.	Description
1	Company address
2	Product type
3	Product number and Serial number
4	Model number
5	Mains supply
6	Max. operating pressure
7	Liquid temperature
8	Barcode
9	Production code
10	Nominal flow rate and maximum flow rate
11	Normal head and maximum head
12	Technical documents
13	IP class
14	Weight
15	Country of origin
16	QR code
17	Marks of approval

English (GB)

Example: Hydro MPC-E 6 CRNE155-1-1 U1 A-A-A-ABCD

Code	Explanation		Designation
Hydro MPC			System name
F	E: All pumps E Motor or CUE	S: Fixed speed pumps	Curata na tura a
E	F: Fixed speed pumps, 1 CUE	X: Customised system type	System type
6			Number of main pumps
CRNE155-1-1			Pump type
	U1: 3 x 380-415 V, N, PE, 50/60 Hz		
	U2: 3 x 380-415 V, PE, 50/60 Hz	UA: 3 x 440-480 V, PE, 60 Hz UB: 1 x 220-240 V, N, PE, 50/60 Hz	
	U3: 3 x 380-415 V, N, PE, 50 Hz	UC:1 x 220-240 V, N, PE, 50/00 Hz	
	U4: 3 x 380-415 V, PE, 50 Hz		
U1	U5: 3 x 380-415V, N, PE, 60 Hz	UD: 3 x 440-480 V, N, PE, 60 Hz	Voltage code
	U6: 3 x 380-415 V, PE, 60 Hz	UJ: 1 x 208-230 V, PE, 60 Hz UK: 3 x 208-230 V, PE, 60 Hz	
	U7: 1 x 200-240 V, PE, 50/60 Hz	UL: 3 x 460-480 V, PE, 60 Hz	
	U8: 1 x 200-240 V, N, PE, 50/60 Hz		
	U9: 3 x 220-240 V, PE, 60 Hz	UX: CSU variant (special voltage rating)	
	•	unted on the same base frame as the pumps.	
	B: Systems with the control cabinet cer		
	C: Systems with the control cabinet mo control cabinet can be placed up to 2 m	unted on its own base for floor mounting. The petres from the numps	
		unted on its own base for floor mounting. The	
	control cabinet can be placed up to 50		
	D: Systems with the control cabinet mo cabinet can be placed up to 2 metres fr	unted on its own base frame. The control rom the pumps.	
	D: Systems with the control cabinet mo cabinet can be placed up to 50 ft from t	unted on its own base frame. The control	
А		trol cabinet mounted on the same base frame	Design
	as the pumps.	200.g.	
	F: APAC design. Systems with the cont	rol cabinet centred on the base frame.	
	G: APAC design. Systems with the con	trol cabinet mounted on its own base for floor	
	mounting. The control cabinet can be p	laced up to 2 metres from the pumps.	
	H: APAC design. Systems with the control cabinet can be placed up to	trol cabinet mounted on its own base frame. o 2 metres from the pumps.	
	I: APAC design. Systems with the contr control cabinet can be placed up to 2 m	ol cabinet prepared for wall mounting. The netres from the pumps.	
	W: Systems with the control cabinet pre can be placed up to 2 metres from the	epared for wall mounting. The control cabinet pumps.	
	A: E		
A	B: DOL		Starting method
	C: SD		
	A: Stainless steel manifold and base fra	ame, and standard valves	
	B: Stainless steel manifold, base frame	and valves	
	C: Galvanised steel manifold and base	frame, and standard valves	
A	D: Stainless steel manifold, galvanised	Material combination	
		frame painted black, and standard valves	
	I: Stainless steel manifold and base fra	me painted black, and standard valves	
	X: Customised material combination		
	A: Standard hydraulic, PN 16	N: PN 10 pressure rating	
	B: Pilot pump	O: PN 25 pressure rating	
	C: Bypass	P: Low prepressure	
	D: NRV on inlet	Q: PN 40 pressure rating	
	E: Elbow manifold	R: RPM = 50 Hz	
	F: No inlet manifold	S: Customised variant	
ABCD	G: Diaphragm tank	T: Certificate	Option
	H: Dry-running protection	U: Undersized motor	
	I: Repair switch	V: Standard controls with options	
	J: Redundant sensor or switch	W: Customised controls	
	K: 1 free pump position	3W: Hydro DDD panel	
	L: 2 free pump position	X: More than 4 options	
	M: 3 free pump position	Y: Control cabinet with double door	

Nameplate



Nameplate, IO 351A



Nameplate, IO 351B

Description
Type designation
Product and version numbers
Permissible supply voltage, frequency and maximum power consumption
Production code (year and week)
Serial number

Type key

Example: IO 35 1 B

Code	Explanation
IO	Input-output module
35	Controller series
1	Model number
	A: For pumps with fixed speed
В	B: For pumps with fixed speed and pumps in F- systems controlled by external frequency converters or the CUE, or as input-output module

2.4 Identification, CU 352

Nameplate



Nameplate, CU 352

Pos.	Description
1	Type designation
2	Product and version numbers
3	Permissible supply voltage, frequency and maximum power consumption
4	Production code (year and week)
5	Serial number

Type key Example: CU 35 2 O

Code	Explanation
CU	Control unit
35	Controller series
2	Model number
0	For panel mounting

2.5 Software label

The software label is placed on the back of the CU 352.

1. Control MPC	3. Hydr	o MPC —	\sim	3
2. C-MPC options	4. H-MPC	options	5. Pump data —	
				4
				1
				11
				1

Software label

Pos.	Description
1	Control MPC - GSC file number
2	Control MPC options - GSC file numbers
3	Hydro MPC - GSC file number ¹⁾
4	Hydro MPC options - GSC file numbers 1)
5	Pump data - GSC file number ²⁾

1) Applies only to systems.

2) Applies only to CR, CRI, CRN, CRE and CRIE pumps.



A GSC (Grundfos Standard Configuration) file is a configuration data file.

3. Technical data

nalieh (C

3.1 Pressure

Inlet pressure

The Hydro MPC systems can operate with a positive inlet pressure (precharged pressure system) or with a negative inlet pressure (vacuum at the inlet manifold).

We recommend that you calculate the inlet pressure in these cases:

- Water is drawn through long pipes.
- Water is drawn from depths.
- Inlet conditions are poor.



In this document, the term "inlet pressure" is defined as the pressure or vacuum which can be measured immediately before the system.

To avoid cavitation, make sure that there is a minimum inlet pressure on the inlet side of the system. The minimum inlet pressure H in metres of head can be calculated as follows: $H = p_b \times 10.2 - NPSH - H_f - H_V - H_S$

p _b	Barometric pressure in bar. Barometric pressure can be set to 1 bar. In closed systems, p _b indicates the system pressure in bar.
	Net Positive Suction Head in metres of head.
NPSH	NPSH can be read from the NPSH curve at the highest flow which the individual pump will be delivering.
	Friction loss in inlet manifold in metres of head at the highest flow the individual pump will be delivering.
H _f	Note: If a non-return valve is installed on the inlet side of the pump, the friction loss in the valve must be added. See the manufacturer's data.
H _v	Vapour pressure in metres of head.
H _s	Safety margin of min. 0.5 metres of head.

-X/-

You need to convert the head in metres to feet.

Maximum inlet pressure

See the CR, CRI, CRN installation and operating instructions supplied with this system.

Operating pressure

As standard, the maximum operating pressure is 16 bar. On request, Grundfos offers Hydro MPC systems with a maximum operating pressure higher than 16 bar.

Operating pressure

As standard, the maximum operating pressure is 232 psi (16 bar) for Hydro MPC CR, CRE and 145 psi (10 bar) for Hydro MPC CME.

On request, Grundfos offers Hydro MPC systems with a maximum operating pressure higher than 232 psi (16 bar).

3.2 Temperature

Liquid temperature	5-60 °C
Ambient temperature	0-40 °C

Higher liquid temperature capability is available on request.

3.3 Relative humidity

Maximum 95 %.

3.4 Sound pressure level

See the installation and operating instructions for the CR pumps. The sound pressure level for a number of pumps can be calculated as follows:

 $L_{max} = L_{pump} + (n-1) \times 3$

L _{max}	Maximum sound pressure level	
L _{pump}	Sound pressure level for one pump	
n	Number of pumps	

3.5 Electrical data

Supply voltage

See the nameplate.

Backup fuse

See the wiring diagram supplied with the system.

Digital inputs

Open-circuit voltage	24 VDC
Closed-circuit current	5 mA, DC
Frequency range	0-4 Hz



All digital inputs are supplied with PELV voltage (Protective Extra-Low Voltage).

Analog inputs

	0-20 mA
Input current and voltage	4-20 mA
	0-10 V
Tolerance	± 3.3 % of full scale
Repetitive accuracy	± 1 % of full scale
Input resistance, current	< 250 Ω
Input resistance, voltage, CU 352	50 kΩ ± 10 %
Input resistance, voltage, IO 351	> 50 kΩ ± 10 %
Supply to sensor	24 V, maximum 50 mA, short-circuit protected



All analog inputs are supplied with PELV voltage (Protective Extra-Low Voltage).

Digital outputs (relay outputs)

Maximum contact load	240 VAC, 2 A
Minimum contact load	5 VDC, 10 mA

All digital outputs are potential-free relay contacts.



Some outputs have a common C terminal. For further information, see the wiring diagram supplied with the system.

Inputs for PTC sensor or thermal switch

For PTC sensors to DIN 44082. Thermal switches can also be connected.

Open-circuit voltage	12 VDC ± 15 %
Closed-circuit current	2.6 mA, DC



Inputs for PTC sensors are electrically separated from the other inputs and outputs of the system.

4.1 Functions of terminals, CU 352



Functions of terminals, CU 352

Pos.	Default settings
1	Outlet pressure
2	Inlet pressure (disabled if no sensor is connected)
3	Configurable analog input (disabled if no sensor is connected)
4	PC Tool connection, TTL
5	Ethernet connection
6	External start/stop
7	Water shortage, pressure/level switch
8	Optional CIM card
9	PC Tool connection, USB

4.2 Functions of terminals, IO 351A and IO 351B

4.2.1 IO 351A



TM081694

Terminal groups

The module can be divided into these groups:

Group 1	Connection of power supply
Group 2	Digital outputs 1-3
Groups 3A, 3C	Digital inputs GENIbus
Group 4A	Inputs for PTC sensor or thermal switch

4.2.2 IO 351B

TM032110



Terminal groups

The module can be divided into these groups:

Group 1	Connection of power supply
Group 2	Digital outputs 1-3
	Digital inputs
Groups 3A, 3B, 3C	Analog inputs and outputs
	GENIbus
Groups 4A, 4B	Inputs for PTC sensor or thermal switch
Group 5	Digital outputs 4-7

4.2.3 Overview of inputs and outputs of modules

Туре	Pump module A	Pump module B	IO module B
Analog input	Not used	Not used	2
Analog output	-	3	Not used
Digital input	3	9	9
PTC input	3	6	Not used
Digital output	3	7	7

The table below shows the modules and the GENIbus number of the individual system types.

System type and number of pumps		Module required in addition to the CU 352	GENIbus number	
E		-	-	
ES	up to four pumps	А	31	
ES	five or six pumps	В	31	
ED	up to five pumps	А	31	
ED	six pumps	В	31	
EDF	up to six pumps	В	31	
EF	up to three pumps	В	31	
EF	four to six pumps	B + B	31 + 32	
F	up to three pumps	В	31	
F	four to six pumps	B + B	31 + 32	
S	up to three pumps	А	31	
S	four to six pumps	В	31	
		General module	41	
		Operating light module	41	
		General module + operating light module	41 + 42	

4.2.4 System type and IO module variants

.	Maximum		GENIbus a			address Pump number				
System type	number of pumps	Controller/module	Module	E-pump	1	2	3	4	5	6
E	6	CU 352		1-6	Е	Е	E	Е	Е	E
	4 -	CU 352	-	1	Е	-	-	-	-	-
50	4 -	IO 351A	31	-	-	S	S	S	-	-
ES -	6 -	CU 352	-	1	Е	-	-	-	-	-
	0 -	IO 351B	31	-	-	S	S	S	S	S
	F	CU 352	-	1-2	Е	Е	-	-	-	-
50	5 -	IO 351A	31	-	-	-	S	S	S	-
ED ·	0	CU 352	-	1-2	E	E	-	-	-	-
	6 -	IO 351B	31	-	-	-	S	S	S	S
		CU 352	-	-	-	-	-	-	-	-
EDF 6	6 -	IO 351B	31	-	EF	EF	S	S	S	S
· · · · · · ·		CU 352	-	-	-	-	-	-	-	-
EF 6	6	IO 351B	31	-	EF	EF	EF	-	-	-
	-	IO 351B	32	-	-	-	-	EF	EF	EF
		CU 352	-	-	-	-	-	-	-	-
F	6	IO 351B	31	-	F/S	F/S	F/S	-	-	-
	-	IO 351B	32	-	-	-	-	F/S	F/S	F/S
	0	CU 352	-	-	-	-	-	-	-	-
	3 -	IO 351A	31	-	S	S	S	-	-	-
S ·	0	CU 352	-	-	-	-	-	-	-	-
	6 –	IO 351B	31	-	S	S	S	S	S	S
Accessory						-			-	-
• •		IO 351B	41 ³⁾	-	D	ata exch	ange, fo	r instanc	e to a Pl	LC
All		2 x IO 351B	41, 42 ⁴⁾							

3) Interface module or operating module.

4) Interface module and operating module.

Legend

Pump number	Description
E	0.37 to 22 kW are E-pumps with integrated frequency converter. 30 to 55 kW are variable-speed pumps controlled by Grundfos CUE frequency converters.
S	Mains-operated pump.
EF	Variable-speed pump controlled by an external frequency converter (not CUE).
F/S	Mains-operated pump or variable-speed pump controlled via a common frequency converter.

This section shows the internal and external connections. The section is split up according to the various system types.

Abbreviations used:

DI: Digital input

DO: Digital output

AO: Analog output

AI: Analog input

C: Common.

E systems, CU 352

Group	Terminal	Designation	Data	Diagram			
	L	Connection to phase conductor		CU 352 L-L			
1	N	Connection to neutral conductor	- 1 × 100-240 VAC ± 10 %, 50/60 Hz	N-N			
	PE	Connection to protect	ive earth	— ⊕-PE			
	A1	RS-485 A					
	Y1	RS-485 GND	- GENIbus	CU 352 IO 351			
2	B1	RS-485 B	- (Fix the screen with a cable clamp.)	Y1Y			
		Functional earth		— B1+↓↓↓B ↓ ↓ ↓ ↓			
3	Connection to	external fieldbus. See in	stallation and operating instructions for the CI	IM module.			
4	0 V +12 VDC	 Connection to battery 	Backup battery				
	10	DI1					
	11	GND	-	10 External stop			
	12	DI2	_ Digital input	111			
5	13	GND	-	12 — Water			
	14	DI3	-	13 shortage			
		All terminals (except mains terminals) must only be connected to voltages not exceeding 16 V _{rms} and 22.6 V _{peak} or 35 VDC.					
		Ethernet RJ45					
6	External comp	uting devices connected	to the Ethernet connection must comply with	the standards IEC 60950 and UL 6095			
7		GENIbus	Service connection				
	47	+24 V	Supply to sensor. Short-circuit-protected 30 mA	47 >			
	50	+24 V	Supply to sensor. Short-circuit-protected 30 mA	50 Pressure			
	51	Al1	Input for analog signal, 0/4-20 mA or 0-10 V	51			
8	53	+24 V	Supply to sensor. Short-circuit-protected 30 mA	53			
	54	AI2	- Input for analog signal, 0/4-20 mA or 0-10 V	54			
	57	AI3	- Input for analog signal, 0/4-20 MA of 0-10 V	57			
	58	GND ⁵⁾					
		except mains terminals) i V _{rms} and 22.6 V _{peak} or 3	must only be connected to voltages not 5 VDC.	- 58			
9		USB port	USB 2.0, type B				
	70		С	70			
	71	 Relay 1	NO	71			
	72	_	NC	72			
10	73		С	73			
	74	— Relay 2	NO	74			

⁵⁾ GND is separated from other earth connections.

ES systems, IO 351, GENIbus number 31

Group	Terminal	Designation	Data	Diagram for standard configuration
	L	— Phase conductor		
	L		— 1 × 100-240 VAC ± 10 %, 50/60 Hz	
	N	— Neutral conductor		IO 351
1	Ν			LL
				N-N
		— PE		⊜−PE
	76	DO1, 2, 3 C		IO 351
	76	DO1, 2, 3 C		Common
	77	DO1 NO	Relay contact, NO	
2	79	DO2 NO	Maximum load: 240 VAC, 2 A	\sim -77 \longrightarrow P2, on/off
			— Minimum load: 5 VDC, 10 mA	$-79 \longrightarrow P3$, on/off
	81	DO3 NO		$-81 \longrightarrow P4$, on/off
	10	DI1		
	10 12	DI1 DI2		
	12	DI3	— Digital input	IO 351 10— External stop, P2
3A	14	GND		12 — External stop, P3
54			ed to voltages of maximum 16 V _{rms} and 22.6	- 14 — External stop, P4
	V _{peak} or 35 VI		to voltages of maximum to v _{rms} and 22.0	15 Common, GND
			ops for which the controller is designed.	—
	53	+24 V	Supply to sensor. Max. 50 mA	
			Supply to sensor. Max. 50 mA	- IO 351
	53 55 57	+24 V GND Al1		53 55
3A	55	GND	Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	53 55
3A	55 57 60	GND Al1 Al2	— Input for analog signal, 0/4-20 mA or 0-10 V	- 53 55 ├ Cannot be used. - 57
3A	55 57 60	GND AI1 AI2 must only be connected		_ 53 55 ├ Cannot be used.
3A	55 57 60 The terminals	GND AI1 AI2 must only be connected	— Input for analog signal, 0/4-20 mA or 0-10 V	- 53 55 ├ Cannot be used. - 57
3A	55 57 60 The terminals V _{peak} or 35 VI	GND AI1 AI2 must only be connecte DC.	— Input for analog signal, 0/4-20 mA or 0-10 V	- 53 55 ├ Cannot be used. - 57
ЗА	55 57 60 The terminals V _{peak} or 35 VI A	GND AI1 AI2 must only be connecte DC. RS-485 A	— Input for analog signal, 0/4-20 mA or 0-10 V	- 53 55 ├ Cannot be used. - 57
	55 57 60 The terminals V _{peak} or 35 VE A A	GND AI1 AI2 must only be connecte DC. RS-485 A RS-485 A	— Input for analog signal, 0/4-20 mA or 0-10 V	- 53 55 - 57 60
3A 3C	55 57 60 The terminals V _{peak} or 35 VI A A Y	GND AI1 AI2 must only be connecte DC. RS-485 A RS-485 A RS-485 GND ⁶⁾	— Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6	- 53 55 - 57 60
	55 57 60 The terminals V _{peak} or 35 VE A A Y Y	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾	— Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — — — — GENIbus (internal)	- 53 55 - 57 60
	55 57 60 The terminals V _{peak} or 35 VE A A Y Y Y B	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 B	— Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — — — — GENIbus (internal)	- 53 55 - 57 60
	55 57 60 The terminals V _{peak} or 35 VE A A Y Y Y B	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 B RS-485 B	— Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — — — — GENIbus (internal)	- 53 55 - 57 60
	55 57 60 The terminals V _{peak} or 35 VI A A Y Y Y B B B B	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 B RS-485 B Functional earth	 Input for analog signal, 0/4-20 mA or 0-10 V ad to voltages of maximum 16 V_{rms} and 22.6 GENIbus (internal) (Fix the screen with a cable clamp.) 	- 53 55 - 57 60
	55 57 60 The terminals V _{peak} or 35 VE A A Y Y Y B B B B B 30	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 B RS-485 B Functional earth PTC1	— Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — — — — GENIbus (internal)	$\begin{bmatrix} 53\\55\\-57\\60 \end{bmatrix}$ Cannot be use d. $\begin{bmatrix} 10 351\\-8 \\ 10 \end{bmatrix}$ CU 352 $\begin{bmatrix} CU 352\\-8 \\ 10 \end{bmatrix}$ $\begin{bmatrix} CU 352\\-8 \\ 10 \end{bmatrix}$
	55 57 60 The terminals V _{peak} or 35 VE A A Y Y Y B B B B B 30 32	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 B RS-485 B RS-485 B Functional earth PTC1 PTC2	 Input for analog signal, 0/4-20 mA or 0-10 V ad to voltages of maximum 16 V_{rms} and 22.6 GENIbus (internal) (Fix the screen with a cable clamp.) 	$\begin{bmatrix} 53\\55\\-57\\60 \end{bmatrix}$ Cannot be use d. $\begin{bmatrix} 10 351\\-8 \\ 10 351\\-8 \\ 10 351 \end{bmatrix}$ CU 352 $\begin{bmatrix} CU 352\\-8 \\ 10 \\ 10 \end{bmatrix}$
3C	55 57 60 The terminals V _{peak} or 35 VE A A Y Y Y B B B B B B 30 32 34 35	GND Al1 Al2 must only be connected DC. RS-485 A RS-485 GND ⁶⁾ RS-485 GND ⁶⁾ RS-485 B RS-485 B RS-485 B Functional earth PTC1 PTC2 PTC3 GND, PTC	 Input for analog signal, 0/4-20 mA or 0-10 V ad to voltages of maximum 16 V_{rms} and 22.6 GENIbus (internal) (Fix the screen with a cable clamp.) 	$\begin{bmatrix} 53\\55\\60 \end{bmatrix}$ Cannot be use d. $\begin{bmatrix} 0 351\\A\\Y\\B\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	
	17	GND		
	18	AO4	Analog output, 0-10 V	
	20	DI5	Digital input	
	21	GND		Cannot be used.
	22	AO5	Analog output, 0-10 V	
3B	24	DI6	Digital input	
30	25	GND		
	26	AO6	Analog output	
	42	DI7		
	44	DI8	Digital input	42 External stop, P5
	46	DI9		44 — External stop, P6 99 — 46 47
	47	GND		47
	Fit jumpers ins	tead of the external		
	36	PTC4	Input for PTC sensor or thermal switch IO 351 36	
	38	PTC5		IO 351
	40	PTC6		
4B	41	GND, PTC		— 38———————————————————————————————————
	Fit jumpers if n	o PTC sensor or the		
	The terminals V _{peak} or 35 VD		cted to voltages of maximum 16 $V_{\rm rms}$ and 22.6	GND, PTC
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		\sim - 82 \rightarrow P5, on/off
	84	DO5 NO		83 Common
	85	DO5 C	Relay contact, NO -84 -> P6, on/off Maximum load: 240 VAC, 2 A 85 Minimum load: 5 VDC, 10 mA -86	$-$ 84 \rightarrow P6, on/off
5	85	DO5 C		
	86	DO6 NO		
	87	DO6 C		87
	87	DO6 C		
	88	DO7 NO		<u> </u>
	89	DO7 C		

ED systems, IO 351, GENIbus number 31

English
(GB)

Terminal	Designation	Data	Diagram for standard configuration
L	- Phase conductor		
L		— 1 × 100-240 VAC + 10 % 50/60 Hz	
N	- Neutral conductor		IO 351
N			L
			N-N
	— PF		⊜−PE
		_	-76 - Common
79	DO2 NO		\sim -77 \longrightarrow P3, on/off
81	DO3 NO		$-79 \longrightarrow P4$, on/off
10	DI1		$-81 \rightarrow P5$, on/off
			10.254
		— Digital input	IO 351 10—— External stop, P3
15			12 — External stop, P4
		_	External stop, P5
Fit jumpers ins	tead of the external st	ops for which the controller is designed.	
53	+24 V	Supply to sensor. Max. 50 mA	– IO 351
55	GND		53
57	Al1	—— Input for analog signal, 0/4-20 mA or 0-10 V	55 Cannot be used.
60	AI2		- 57
		d to voltages of maximum 16 $\mathrm{V}_{\mathrm{rms}}$ and 22.6	60
A	RS-485 A		
A	RS-485 A		
Y	RS-485 GND ⁷⁾		IO 351 CU 352
Y	RS-485 GND ⁷⁾	GENIbus (internal)	A A1
В	RS-485 B	(Fix the screen with a cable clamp.)	Y +++++ Y1 B -++++ B1
В	RS-485 B		<u>∔</u> <u>ч</u> <u>ч</u> <u></u>
Functional earth	_		
30	PTC1		
32	PTC2	Insuit for DTC company on the second south the	IO 351
34	PTC3	- Input for PIC sensor or thermal switch	30 PTC, P3
35	GND, PTC		32
	DTO		− 34 −−−⊂⊂− PTC, P5
Fit jumpers if r	o PTC sensor or therr	nai switch is connected.	
	$ \begin{array}{c c} L\\ N\\ N\\ N\\ N\\ \hline\\ 0 \\ \hline\\ 0 \\ \hline\\\\ \hline\\\\ \hline\\ 76\\ \hline\\ 70\\ \hline\\ 81\\ \hline\\ 10\\ \hline\\ 79\\ \hline\\ 81\\ \hline\\ 70\\ \hline\\ 7\\ \hline\\ 8\\ \hline 8\\ \hline$	LPhase conductorNNeutral conductorN $ -$	$\begin{tabular}{ c c c c } \hline L & Phase conductor \\ \hline L & Phase conductor \\ \hline N & Neutral condu$

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	
	17	GND		
	18	AO4	Analog output, 0-10 V	
	20	DI5	Digital input	
	21	GND		Cannot be used.
	22	AO5	Analog output, 0-10 V	
3B	24	DI6	Digital input	
30	25	GND		
	26	AO6	Analog output	
	42	DI7		
	44	DI8	Digital input	42 — External stop, P6
	46	D19		
	47	GND		40
	Fit jumpers ins	tead of the external		
	36	PTC4		
	38	PTC5	Input for PTC sensor or thermal switch IO 351 36 PTC, P6	IO 351
	40	PTC6		
4B	41	GND, PTC		
	Fit jumpers if n	o PTC sensor or the	40	
		The terminals must only be connected to voltages of maximum 16 $\rm V_{rms}$ and 22.6 $\rm V_{peak}$ or 35 VDC.		GND, PTC
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		$-$ 22 \rightarrow P6, on/off
	84	DO5 NO		83 ← Common 83
	85	DO5 C	Relay contact NO	- 84
5	85	DO5 C	Maximum load: 240 VAC, 2 A	85
	86	DO6 NO	Minimum load: 5 VDC, 10 mA	
	87	DO6 C		87
	87	DO6 C		87
	88	DO7 NO		L
	89	DO7 C		

EDF systems, IO 351, GENIbus number 31

English
(GB)

Group	Terminal	Designation	Data	Diagram for standard configuratio
	L	— Phase conductor		
	L		— 1 × 100-240 VAC ± 10 %, 50/60 Hz	
	N	— Neutral conductor		IO 351
1	N			L_L
1				N-N
	<u>+</u>	— PE		€−PE
	<u>+</u>			
	76	DO1, 2, 3 C		IO 351
	76	DO1, 2, 3 C		Common
	77	DO1 NO	Relay contact, NO	
2	79	DO2 NO	Maximum load: 240 VAC, 2 A	\sim -77 \longrightarrow P4, on/off, mains
	81	DO3 NO	Maximum Ioad: 240 VAC, 2 A Minimum Ioad: 5 VDC, 10 mA Digital input	$-79 \longrightarrow P5$, on/off, mains $-81 \longrightarrow P6$, on/off, mains
	10	DI1		
	12	DI2		IO 351
	14	DI3	— Digital input	External stop, P1
3A	15	GND		12—— External stop, P2
0/1			d to voltages of maximum 16 V _{rms} and 22.6	- 14 External stop, P3 15Common, GND
0,1	V _{peak} or 35 VE	DC.	ed to voltages of maximum 16 V _{rms} and 22.6	
0,1	V _{peak} or 35 VE Fit jumpers ins	DC. stead of the external st	ops for which the controller is designed.	
	V _{peak} or 35 VE Fit jumpers ins 53	DC. stead of the external st +24 V		15Common, GND
	V _{peak} or 35 VE Fit jumpers ins 53 55	DC. stead of the external st +24 V GND	ops for which the controller is designed.	- IO 351 53
3A	V _{peak} or 35 VE Fit jumpers ins 53 55 57	DC. stead of the external st +24 V GND Al1	ops for which the controller is designed. Supply to sensor. Max. 50 mA	- IO 351 - 53 - 55
	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60	DC. stead of the external st +24 V GND Al1 Al2	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 53 55 Cannot be used.
	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60	DC. stead of the external st +24 V GND Al1 Al2 must only be connected	ops for which the controller is designed. Supply to sensor. Max. 50 mA	- IO 351 - 53 - 55
	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals	DC. stead of the external st +24 V GND Al1 Al2 must only be connected	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 53 55 - 57 Common, GND Cannot be used.
	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VE	DC. stead of the external st +24 V GND AI1 AI2 must only be connected DC.	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 53 55 - 57 Common, GND Cannot be used.
	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VE A	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 53 55 - 57 Common, GND Cannot be used.
3A	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VE A A	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 53 55 - 57 60 Cannot be used.
	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VE A A Y	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 —	- IO 351 53 55 - 57 60 Cannot be used.
3A	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VE A A Y Y	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾ RS-485 GND ⁸⁾	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	- IO 351 53 55 - 57 60 Cannot be used.
3A	Vpeak or 35 VE Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VE A Y P B	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾ RS-485 GND ⁸⁾ RS-485 GND ⁸⁾	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	- IO 351 53 55 - 57 60 Cannot be used.
3A	Vpeak or 35 VE Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VE A Y P B	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾ RS-485 GND ⁸⁾ RS-485 B RS-485 B	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	- IO 351 53 55 - 57 60 Cannot be used.
3A	V _{peak} or 35 VE Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VE A A Y Y B B B 	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾ RS-485 GND ⁸⁾ RS-485 B RS-485 B Functional earth	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal) (Fix the screen with a cable clamp.) —	$ \begin{array}{c} 15 \\ \hline Common, GND \\ \hline 10 351 \\ \hline 57 \\ 60 \\ \hline 0 351 \\ \hline CU 352 \\ A \\ Y \\ B \\ \downarrow \\ \hline U 351 \\ \hline 0 351 \\ \hline 0 351 \\ \hline \end{array} $
3A	Vpeak or 35 VE Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VE A Y Y B B 30	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾ RS-485 GND ⁸⁾ RS-485 B RS-485 B Functional earth PTC1	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	$ \begin{array}{c} 15 \\ \hline \\ \hline \\ 10 351 \\ \hline \\ 57 \\ 60 \end{array} \right) Cannot be used. $ $ \begin{array}{c} IO 351 \\ \hline \\ 57 \\ 60 \end{array} \right) CU 352 \\ A1 \\ Y1 \\ B1 \\ \downarrow \end{array} $ $ \begin{array}{c} IO 351 \\ \hline \\ 10 351 \\ \hline \\ 30 \end{array} - \begin{array}{c} CU 352 \\ A1 \\ Y1 \\ B1 \\ \downarrow \end{array} \right) PTC, P1 $
3A	Vpeak or 35 VE Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VE A Y B B	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ⁸⁾ RS-485 GND ⁸⁾ RS-485 B RS-485 B RS-485 B Functional earth PTC1 PTC2	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal) (Fix the screen with a cable clamp.) —	$ \begin{array}{c} 15 \\ \hline Common, GND \\ \hline 10 351 \\ \hline 57 \\ 60 \\ \hline 0 351 \\ \hline CU 352 \\ A \\ Y \\ B \\ \downarrow \\ \hline U 351 \\ \hline 0 351 \\ \hline 0 351 \\ \hline \end{array} $

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	IO 351
	17	GND		16 ———— VFD1, ready
	18	AO4	Analog output, 0-10 V	── 17 ── VFD1, GND ── 18 ──(र)── VFD1, speed
	20	DI5	Digital input	20 VFD1, speed
	21	GND		21 VFD2, GND
	22	AO5	Analog output, 0-10 V	── 22 ── VFD2, spee d 23
3B	24	DI6	Digital input	
50	25	GND		242526
	26	AO6	Analog output	<u>20</u> F
	42	DI7		
	44	DI8	Digital input	42 — External stop, P4 44 — External stop, P5 । ।
	46	DI9		44 → External stop, P5 46 → External stop, P6 47 → Common_GND
	47	GND		47 Common, GND
	Fit jumpers ins	tead of the external	stops for which the controller is designed.	
	36	PTC4	Input for PTC sensor or thermal switch IO 351	
	38	PTC5		
	40	PTC6		
4B	41	GND, PTC		9TC, P5
	Fit jumpers if no PTC sensor or thermal switch is connected.			
	The terminals V _{peak} or 35 VD	•	cted to voltages of maximum 16 $\mathrm{V}_{\mathrm{rms}}$ and 22.6	GND, PTC ₽
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		$-2.82 \longrightarrow VFD1$, start
	84	DO5 NO		$- 83 \leftarrow Common$
	85	DO5 C	Relay contact, NO ✓ - 84 → VFD2, start Maximum load: 240 VAC, 2 A 85 ← Common Minimum load: 5 VDC, 10 mA ~ - 86 → P3, on/off, main	
5	85	DO5 C		
	86	DO6 NO		
	87	DO6 C		87 ← Common
	87	DO6 C		87
	88	DO7 NO		└ <u></u> 89
	89	DO7 C		

17

EF systems, module B1, IO 351, GENIbus number 31

English
(GB)

L N N 	 Phase conductor Neutral conductor PE DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3 	— 1 × 100-240 VAC ± 10 %, 50/60 Hz	$\begin{bmatrix} IO \ 351 \\ N - N \\ \textcircledleft \\ \hline \\ $
N N — — — 76 76 76 77 79 81 10 12 14	Neutral conductor PE DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Relay contact, NO Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	$\begin{bmatrix} L - L \\ N - N \\ \oplus - PE \end{bmatrix}$
N 	PE DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Relay contact, NO Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	$\begin{bmatrix} L - L \\ N - N \\ \oplus - PE \end{bmatrix}$
76 76 77 79 81 10 12 14	PE DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	$\begin{bmatrix} N - N \\ \textcircledleft \\ \end{matrix} \\ \end{matrix}$
76 76 77 79 81 10 12 14	DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	
76 76 77 79 81 10 12 14	DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	$ \begin{array}{c} \text{IO 351} \\ \hline 76 \\ \hline 76 \\ \hline -77 \\ \hline -79 \\ \hline 81 \end{array} $ Cannot be used.
76 76 77 79 81 10 12 14	DO1, 2, 3 C DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	Cannot be use d.
76 76 77 79 81 10 12 14	DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	Cannot be use d.
76 77 79 81 10 12 14	DO1, 2, 3 C DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	Cannot be use d.
77 79 81 10 12 14	DO1 NO DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	Cannot be used.
79 81 10 12 14	DO2 NO DO3 NO DI1 DI2 DI3	Maximum load: 240 VAC, 2 A Minimum load: 5 VDC, 10 mA	Cannot be use d.
81 10 12 14	DO3 NO DI1 DI2 DI3	— Minimum load: 5 VDC, 10 mA —	IO 351
10 12 14	DI1 DI2 DI3	_	IO 351
12 14	DI2 DI3	— Digital input	IO 351
14	DI3	— Digital input	IO 351
		— Digital input	
15			10—External stop, P1
	GND		12—— External stop, P2
_{eak} or 35 VE	DC.	-	External stop, P3
		Supply to sensor. Max. 50 mA	- IO 351
			53 55
		ad to voltage of movimum 16 V and 22 6	- 57
The terminals must only be connected to voltages of maximum 16 V_{rms} and 22.6 V_{peak} or 35 VDC.			60)
			IO 351 CU 352
			A A1
			Y Y1
B RS-485 B	_		
30	PTC1		~
32	PTC2		IO 351
34	PTC3	— Input for PTC sensor or thermal switch	30 ──── ────────────────────────────────
35	GND, PTC		32
jumpers if r	no PTC sensor or therr	nal switch is connected.	— 34 <u>— t→</u> PTC, P3
	ak or 35 VE umpers ins 53 55 57 60 e terminals ak or 35 VE A A Y B B J 30 32 34 35 umpers if r e terminals	ak or 35 VDC.umpers instead of the external st53+24 V55GND57Al160Al2terminals must only be connectedak or 35 VDC.ARS-485 AARS-485 GND $^{9)}$ YRS-485 GND $^{9)}$ YRS-485 BBRS-485 BJ	umpers instead of the external stops for which the controller is designed. 53 +24 V Supply to sensor. Max. 50 mA 55 GND 57 Al1 60 Al2 Input for analog signal, 0/4-20 mA or 0-10 V 6 terminals must only be connected to voltages of maximum 16 V _{rms} and 22.6 ak or 35 VDC. A RS-485 A Y RS-485 GND ⁹⁾ Y RS-485 GND ⁹⁾ Y RS-485 GND ⁹⁾ B RS-485 B Imput for PTC sensor or thermal switch is connected. 30 PTC1 32 PTC2 34 PTC3 35 GND, PTC umpers if no PTC sensor or thermal switch is connected. terminals must only be connected to voltages of maximum 16 V _{rms} and 22.6

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	IO 351
	17	GND		16 ——— VFD1, ready
	18	AO4	Analog output, 0-10 V	17 VFD1, GND 18 () VFD1, speed
	20	DI5	Digital input	20 VFD1, speed
	21	GND		21 VFD2, GND
	22	AO5	Analog output, 0-10 V	── 22 ─(<u>\</u>)── VFD2, speed 23 ── \ VFD3, ready
3B	24	DI6	Digital input	24 VFD3, GND
30	25	GND		24 VFD3, GND 25 VFD3, speed
	26	AO6	Analog output	— <u>26</u> F
	42	DI7		
	44	DI8	Digital input	42
	46	DI9		44 662.99804 46 6004
	47	GND		47.
	Fit jumpers ins	tead of the external		
	36	PTC4		
	38	PTC5	Input for PTC sensor or thermal switch IO 351 36	
	40	PTC6		
4B	41	GND, PTC		38
	Fit jumpers if n	o PTC sensor or the		
	The terminals V _{peak} or 35 VD		cted to voltages of maximum 16 $\mathrm{V}_{\mathrm{rms}}$ and 22.6	41 F
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		$-$ - 82 \rightarrow VFD1, start
	84	DO5 NO		83 ← Common 83
	85	DO5 C	Relay contact, NO	$-84 \rightarrow VFD2$, start
5	85	DO5 C	Maximum load: 240 VAC, 2 A	85 ← Common 85
	86	DO6 NO	Minimum load: 5 VDC, 10 mA	$-$ - 86 \rightarrow VFD3, start
	87	DO6 C		87 ← Common 87
	87	DO6 C		
	88	DO7 NO		
	89	DO7 C		

EF systems, module B2, IO 351, GENIbus number 32

English
(GB)

	Terminal	Designation	Data	Diagram for standard configuration	۱
	L	— Phase conductor			
	L		— 1 × 100-240 VAC ± 10 %, 50/60 Hz		
	Ν	— Neutral conductor	. 100 2+0 V/O ± 10 /0, 00/00 HZ	IO 351	
1	N			L_L	
				N – N	
		— PE		⊕−PE	
	<u> </u>				
	76	DO1, 2, 3 C		IO 351	
	76	DO1, 2, 3 C			
	77	DO1 NO	Relay contact, NO	76	
2	79	DO2 NO	Maximum load: 240 VAC, 2 A	Cannot be used.	
	81	DO3 NO	— Minimum load: 5 VDC, 10 mA	- 79 - 81	
	10	DI1			
	12	DI2		IO 351	
	14	DI3	— Digital input	External stop, P4	P4
3A	15	GND	—	− 12 — External stop, P5 − 14 — External stop, P6	
	V _{peak} or 35 VI	DC.	ed to voltages of maximum 16 V _{rms} and 22.6 ops for which the controller is designed.	Common, GND	
	V _{peak} or 35 VI	DC.			
	V _{peak} or 35 VI Fit jumpers ins	DC. stead of the external st	ops for which the controller is designed.		
30	V _{peak} or 35 VI Fit jumpers ins 53	DC. stead of the external st +24 V	ops for which the controller is designed. Supply to sensor. Max. 50 mA	- IO 351 53 - 55	
3A	V _{peak} or 35 VI Fit jumpers ins 53 55	DC. stead of the external st +24 V GND	ops for which the controller is designed.	- IO 351 - 53 - 55 } Cannot be used.	
ЗА	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60	DC. stead of the external str +24 V GND AI1 AI2 must only be connected	ops for which the controller is designed. Supply to sensor. Max. 50 mA	- IO 351 53 - 55	
3A	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals	DC. stead of the external str +24 V GND AI1 AI2 must only be connected	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 - 53 - 55 - 57 - 57	
ЗА	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI	DC. stead of the external st +24 V GND AI1 AI2 must only be connected DC.	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 - 53 - 55 - 57 - 57	
ЗА	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI A	DC. stead of the external str +24 V GND Al1 Al2 must only be connected DC. RS-485 A	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 - 53 - 55 - 57 - 57	
	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI A A	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V	- IO 351 53 55 - 57 60 Cannot be use d.	
3A 3C	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI A A Y	DC. stead of the external st +24 V GND AI1 AI2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 —	- IO 351 53 55 - 57 60 Cannot be use d.	
	Vpeak or 35 VI Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VI A A Y Y	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾ RS-485 GND ¹⁰⁾	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	- IO 351 53 55 - 57 60 Cannot be use d.	
	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI A A Y Y B	DC. stead of the external str +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾ RS-485 GND ¹⁰⁾ RS-485 B	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	- IO 351 53 55 - 57 60 Cannot be use d.	
	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI A A Y Y B	DC. stead of the external str +24 V GND AI1 AI2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾ RS-485 GND ¹⁰⁾ RS-485 B RS-485 B RS-485 B	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	- IO 351 53 55 - 57 60 Cannot be use d.	
	V _{peak} or 35 VI Fit jumpers ins 53 55 57 60 The terminals V _{peak} or 35 VI A A Y P B B B 	DC. stead of the external str +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾ RS-485 GND ¹⁰⁾ RS-485 B RS-485 B Functional earth	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal) (Fix the screen with a cable clamp.) —	$= \begin{bmatrix} IO 351 \\ 53 \\ 55 \\ 57 \\ 60 \end{bmatrix} Cannot be use d.$ $= \begin{bmatrix} IO 351 \\ A \\ Y \\ B \\ \downarrow \end{bmatrix} \begin{bmatrix} CU 352 \\ A1 \\ Y1 \\ B1 \\ \downarrow \end{bmatrix}$ IO 351	
	Vpeak or 35 VI Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VI A Y P B B 30	DC. stead of the external st +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾ RS-485 GND ¹⁰⁾ RS-485 B RS-485 B Functional earth PTC1	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal)	$\begin{bmatrix} IO 351 \\ 53 \\ 55 \\ 60 \end{bmatrix}$ Cannot be use d. $\begin{bmatrix} IO 351 \\ 57 \\ 60 \end{bmatrix}$ CU 352 $\begin{bmatrix} CU 352 \\ A1 \\ Y1 \\ B1 \\ \downarrow \end{bmatrix}$ $\begin{bmatrix} IO 351 \\ 30 \end{bmatrix}$	
	Vpeak or 35 VI Fit jumpers ins 53 55 57 60 The terminals Vpeak or 35 VI A A Y B B	DC. stead of the external str +24 V GND Al1 Al2 must only be connected DC. RS-485 A RS-485 A RS-485 GND ¹⁰⁾ RS-485 GND ¹⁰⁾ RS-485 B RS-485 B Functional earth PTC1 PTC2	ops for which the controller is designed. Supply to sensor. Max. 50 mA — Input for analog signal, 0/4-20 mA or 0-10 V ed to voltages of maximum 16 V _{rms} and 22.6 — GENIbus (internal) (Fix the screen with a cable clamp.) —	$= \begin{bmatrix} IO 351 \\ 53 \\ 55 \\ 57 \\ 60 \end{bmatrix} Cannot be use d.$ $= \begin{bmatrix} IO 351 \\ A \\ Y \\ B \\ \downarrow \end{bmatrix} \begin{bmatrix} CU 352 \\ A1 \\ Y1 \\ B1 \\ \downarrow \end{bmatrix}$ IO 351	

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	IO 351
	17	GND		16 ——— VFD4, ready
	18	AO4	Analog output, 0-10 V	
	20	DI5	Digital input	20 VFD4, speed
	21	GND		21 VFD5, GND
	22	AO5	Analog output, 0-10 V	── 22 ── VFD5, speed ── 23 ── VFD6, ready
3B	24	DI6	Digital input	24 VFD6, GND
30	25	GND		24 VFD6, GND 25 VFD6, speed
	26	AO6	Analog output	— <u>26</u>
	42	DI7		
	44	DI8	Digital input	42
	46	DI9		44 46 47
	47	GND		47.
	Fit jumpers ins	tead of the external		
	36	PTC4	Input for PTC sensor or thermal switch	
	38	PTC5		IO 351
	40	PTC6		36
4B	41	GND, PTC		38
	Fit jumpers if n	o PTC sensor or the		
	The terminals V _{peak} or 35 VD		cted to voltages of maximum 16 $\mathrm{V}_{\mathrm{rms}}$ and 22.6	41 F
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		$-$ 82 \rightarrow VFD4, start
	84	DO5 NO		83 ← Common 83
	85	DO5 C	Relay contact, NO	$-$ - 84 \rightarrow VFD5, start
5	85	DO5 C	Maximum load: 240 VAC, 2 A	85 ← Common 85
	86	DO6 NO	Minimum load: 5 VDC, 10 mA	$-$ - 86 \rightarrow VFD6, start
	87	DO6 C		87 ← Common 87
	87	DO6 C		- 88
	88	DO7 NO		89
	89	DO7 C		

21

F systems, module B1, IO 351, GENIbus number 31

English
(GB)

Group	Terminal	Designation	Data	Diagram for standard configuration	n
	L	— Phase conductor			
	L		— 1 × 100-240 VAC ± 10 %, 50/60 Hz		
	N	— Neutral conductor		IO 351	
1	N			_ L-L	
·				N – N	
		— PE		€−PE	
	±				
	76	DO1, 2, 3 C		IO 351	
	76	DO1, 2, 3 C		Common	
	77	DO1 NO	Relay contact, NO		
2	79	DO2 NO	Maximum load: 240 VAC, 2 A	\sim -77 \longrightarrow P1, on/off, mains	
	81	DO3 NO	— Minimum load: 5 VDC, 10 mA	$-79 \longrightarrow P2$, on/off, mains $-81 \longrightarrow P3$, on/off, mains	
	10	DI1			
	12	DI2		IO 351	
	14	DI3			rnal stop, P1
3A	15	GND		12 — External stop, P2	
	The terminals must only be connected to voltages of maximum 16 V_{rms} and 22.6 V_{peak} or 35 VDC.			 14 — External stop, P3 15 Common, GND 	
			ops for which the controller is designed.		
	53	+24 V	Supply to sensor. Max. 50 mA	– IO 351)	
	55	GND		53	
3A	57	Al1	—— Input for analog signal, 0/4-20 mA or 0-10 V 55 Canno		be used.
	60	AI2		- 57	
	The terminals must only be connected to voltages of maximum 16 V_{rms} and 22.6 $V_{peak} \mbox{ or 35 VDC}.$			60	
	A	RS-485 A			
	A	RS-485 A			
	Y	RS-485 GND ¹¹⁾		IO 351 CU 352	
3C	Y	RS-485 GND ¹¹⁾	GENIbus (internal)		
	В	RS-485 B	(Fix the screen with a cable clamp.)	B	
	В	RS-485 B		ŢŢŢŢ	
		Functional earth			
	30	PTC1			
	32	PTC2	— Input for PTC sensor or thermal switch	IO 351	
	34	PTC3		30	
4A	35	GND, PTC		32	
	Fit jumpers if r	no PTC sensor or therr	nal switch is connected.	— 34 — — <u>→</u> PTC, P3	
	The terminals V _{peak} or 35 VE		ed to voltages of maximum 16 V_{rms} and 22.6	GND, PTC	

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	IO 351
	17	GND		16
	18	AO4	Analog output, 0-10 V	
	20	DI5	Digital input	
	21	GND		21
	22	AO5	Analog output, 0-10 V	22 23
3B	24	DI6	Digital input	
30	25	GND		24 25
	26	AO6	Analog output	20
	42	DI7		
	44	DI8	Digital input	42 VFD, ready
	46	DI9		44
	47	GND		47VFD, GND
	Fit jumpers ins	tead of the external		
	36	PTC4	Input for PTC sensor or thermal switch IO 351 36	
	38	PTC5		
	40	PTC6		
4B	41	GND, PTC		38
	Fit jumpers if n	o PTC sensor or the		
	The terminals V _{peak} or 35 VD		cted to voltages of maximum 16 $\mathrm{V}_{\mathrm{rms}}$ and 22.6	41
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		$-$ 82 \rightarrow P1, on/off, VFD
	84	DO5 NO		$83 \leftarrow Common$ 83
	85	DO5 C	Relay contact, NO	$-$ 84 \rightarrow P2, on/off, VFD
5	85	DO5 C	Maximum load: 240 VAC, 2 A	85 Common
	86	DO6 NO	Minimum load: 5 VDC, 10 mA	$-$ - 86 \rightarrow P3, on/off, VFD
	87	DO6 C		$87 \leftarrow Common$
	87	DO6 C		$-$ - 88 \longrightarrow VFD, start
	88	DO7 NO		└── 89 ←── Common

F systems, module B2, IO 351, GENIbus number 32

English
(GB)

Group	Terminal	Designation	Data	Diagram for standard configuration
	L	— Phase conductor		
	L		— 1 × 100-240 VAC ± 10 %, 50/60 Hz	
	N	— Neutral conductor		IO 351
1	Ν			L-L
1				N-N
	<u> </u>	— PE		⊕−PE
	<u> </u>			
	76	DO1, 2, 3 C		IO 351
	76	DO1, 2, 3 C		Common
	77	DO1 NO	Relay contact, NO	
2	79	DO2 NO	Maximum load: 240 VAC, 2 A	\sim -77 \longrightarrow P4, on/off, mains
			— Minimum load: 5 VDC, 10 mA	$-79 \longrightarrow P5$, on/off, mains
	81	DO3 NO		P6, on/off, mains
	10	DI1		
	12	DI2	— Digital input	IO 351
	14	DI3	— Digital Input	10—External stop, P4
3A	15	GND		12 — External stop, P5
	The terminals must only be connected to voltages of maximum 16 V_{rms} and 22.6 V_{peak} or 35 VDC.			External stop, P6
			ops for which the controller is designed.	
	53	+24 V	Supply to sensor. Max. 50 mA	- IO 351
	55 57	GND Al1		53 55
3A			— Input for analog signal, 0/4-20 mA or 0-10 V	
		60 Al2		- 57
	The terminals must only be connected to voltages of maximum 16 V_{rms} and 22.6 $V_{peak}\ or$ 35 VDC.			60)
	A	RS-485 A		
	A	RS-485 A		
	Y	RS-485 GND ¹²⁾		IO 351 CU 352
	Y	RS-485 GND ¹²⁾	 GENIbus (internal)	A A1
3C	В	RS-485 B	(Fix the screen with a cable clamp.)	Y ++++ Y1 B +++ B1
	В	RS-485 B	_	
		Functional earth		
	30	PTC1		
	32	PTC2		IO 351
	34	PTC3	— Input for PTC sensor or thermal switch	30 — C PTC, P4
4A	35	GND, PTC		32
			nal switch is connected.	− 34 <u>−−−亡_</u> PTC, P6
	Fit jumpers if r	no PIC sensor or therr	nai switch is connected.	

Group	Terminal	Designation	Data	Diagram for standard configuration
	16	DI4	Digital input	IO 351
	17	GND		16
	18	AO4	Analog output, 0-10 V	17 18
	20	DI5	Digital input	20
	21	GND		21
	22	AO5	Analog output, 0-10 V	22 23
3B	24	DI6	Digital input	23
	25	GND		25
	26	AO6	Analog output	- 26
	42	DI7		42
	44	DI8	Digital input	44
	46	DI9		46
	47	GND		47.
	36	PTC4		
	38	PTC5	Input for PTC sensor or thermal switch	IO 351
	40	PTC6		36
4B	41	GND, PTC		38
	Fit jumpers if r	o PTC sensor or the	ermal switch is connected.	40
	The terminals V _{peak} or 35 VE		cted to voltages of maximum 16 $V_{\mbox{rms}}$ and 22.6	41
	82	DO4 NO		
	83	DO4 C		IO 351
	83	DO4 C		- $-$ 82 $-$ P4, on/off, VFD
	84	DO5 NO		83 (Common 83
	85	DO5 C	Relay contact, NO	$-$ - 84 \longrightarrow P5, on/off, VFD
5	85	DO5 C	Maximum load: 240 VAC, 2 A	85 ← Common 85
	86	DO6 NO	Minimum load: 5 VDC, 10 mA	$-$ - 86 \rightarrow P6, on/off, VFD
	87	DO6 C		87 ← Common 87
	87	DO6 C		88
				L89
	88	DO7 NO		

S systems, IO 351, GENIbus number 31

Englist
h (GB)

Group	Terminal	Designation	Data	Diagram for standard configuration	۱
-	L	— Phase conductor			
	L		— 1 × 100-240 VAC ± 10 %, 50/60 Hz		
	N	— Neutral conductor		IO 351	
1	N			LL	
I				N-N	
		— PE		⊕−PE	
		. –			
	<u> </u>				
	76	DO1, 2, 3 C		IO 351	
	76	DO1, 2, 3 C		76 Common	
	77	DO1 NO	Relay contact, NO		
2	79	DO2 NO	Maximum load: 240 VAC, 2 A	$-77 \longrightarrow P1$, on/off, mains	
	81	DO3 NO	— Minimum load: 5 VDC, 10 mA	$-79 \longrightarrow P2$, on/off, mains $-81 \longrightarrow P3$, on/off, mains	
	10	DI1			-
	12	DI2		IO 351	
	14	DI3	— Digital input	10—External stop, P1	
3A	15	GND		12 — External stop, P2	
	V _{peak} or 35 VD		 14 — External stop, P3 15 — Common, GND 		
			ops for which the controller is designed.		
	53	+24 V	Supply to sensor. Max. 50 mA	– IO 351	
	55	GND		53 55	
3A	57	Al1	— Input for analog signal, 0/4-20 mA or 0-10 V		
	60	AI2		- 57	
	The terminals V _{peak} or 35 VE		ed to voltages of maximum 16 V_{rms} and 22.6	60	
	Α	RS-485 A			
	Α	RS-485 A			
	Y	RS-485 GND ¹³⁾		IO 351 CU 352	
3C	Y	RS-485 GND ¹³⁾	GENIbus (internal)		
50	В	RS-485 B	(Fix the screen with a cable clamp.)	B-\B1	
	В	RS-485 B		ŢŢŢŢŢŢŢ	
	<u> </u>	Functional earth			
	30	PTC1			_
	32	PTC2	Input for PTC concor or thormal quitch	IO 351	
	34	PTC3	 Input for PTC sensor or thermal switch 	30	
4A	35	GND, PTC		32	
	Fit jumpers if r	o PTC sensor or therr	nal switch is connected.	− 34 − <u>⊂</u> PTC, P3	
		must only be connecte	nal switch is connected. Ind to voltages of maximum 16 V _{rms} and 22.6	– 35 – GND, P	

Group	Terminal	Designation	Data	Diagram for standard configuration	
	16	DI4	Digital input	IO 351	
	17	GND		16	
	18	AO4	Analog output, 0-10 V	17 18	
	20	DI5	Digital input	20	
	21	GND		21	
	22	AO5	Analog output, 0-10 V	22 23	
3B	24	DI6	Digital input	24	6741
30	25	GND		25 	TM086741
	26	AO6	Analog output	20	
	42	DI7			4
	44	DI8	Digital input	42 — External stop, P4	
	46	DI9		44 — External stop, P5 46 — External stop, P6	TM086724
	47	GND		47 Common, GND	TM0
	Fit jumpers ins	stead of the external	stops for which the controller is designed.		
	36	PTC4	Input for PTC sensor or thermal switch	IO 351 36	
	38	PTC5			
	40	PTC6			
4B	41	GND, PTC			25
	Fit jumpers if r	no PTC sensor or th		TM086725	
	The terminals V _{peak} or 35 VE	must only be conne)C.	41 GND, PTC	μ	
	82	DO4 NO			
	83	5010		10.054	
	03	DO4 C			
	83	DO4 C DO4 C		IO 351 $-82 \rightarrow P4$, on/off	
				$-82 \longrightarrow P4$, on/off 83 \leftarrow Common	
	83	DO4 C	Relay contact, NO	$ \begin{array}{c} -82 \longrightarrow P4, \text{ on/off} \\ \hline 83 \longleftarrow Common \\ \hline 83 \\ \hline -84 \longrightarrow P5, \text{ on/off} \end{array} $	
5	83 84	DO4 C DO5 NO	Relay contact, NO Maximum load: 240 VAC, 2 A	$ \begin{array}{c} -82 \longrightarrow P4, \text{ on/off} \\ \hline 83 \longleftarrow Common \\ \hline 83 \longrightarrow P5, \text{ on/off} \\ \hline 85 \longleftarrow Common \end{array} $	
5	83 84 85	DO4 C DO5 NO DO5 C		$ \begin{array}{c} -82 \longrightarrow P4, \text{ on/off} \\ 83 \longleftarrow Common \\ 83 \longrightarrow P5, \text{ on/off} \\ 85 \longleftarrow Common \\ 85 \longleftarrow P6, \text{ on/off} \\ \end{array} $	
5	83 84 85 85	DO4 C DO5 NO DO5 C DO5 C	Maximum load: 240 VAC, 2 A	$ \begin{array}{c} -82 \longrightarrow P4, \text{ on/off} \\ 83 \longleftarrow Common \\ 83 \longrightarrow P5, \text{ on/off} \\ 85 \longleftarrow Common \\ 85 \end{array} $	743
5	83 84 85 85 86	DO4 C DO5 NO DO5 C DO5 C DO6 NO	Maximum load: 240 VAC, 2 A	$ \begin{array}{c} -82 \longrightarrow P4, \text{ on/off} \\ 83 \longleftarrow Common \\ 83 \longrightarrow P5, \text{ on/off} \\ 85 \longleftarrow Common \\ 85 \longleftarrow -86 \longrightarrow P6, \text{ on/off} \\ 87 \longrightarrow Common \\ 87 \longrightarrow -88 \\ \end{array} $	M086743
5	83 84 85 85 86 87	DO4 C DO5 NO DO5 C DO5 C DO6 NO DO6 C	Maximum load: 240 VAC, 2 A	$ \begin{array}{c} -82 \longrightarrow P4, \text{ on/off} \\ 83 \longleftarrow Common \\ 83 \longrightarrow P5, \text{ on/off} \\ 85 \longleftarrow Common \\ 85 \longleftarrow -86 \longrightarrow P6, \text{ on/off} \\ 87 \longrightarrow Common \\ 87 \end{array} $	TM086743

4.2.6 CU 352 and IO 351 installation and operating instructions

See Grundfos Product Center for the CU 352 or IO 351 installation and operating instructions.

5. Fault correction tools

5.1 MPC/CU 352 indicator lights and alarm relay

See Grundfos Product Center for CU 352 or IO 351 installation and operating instructions.

5.2 MPC display

5.2.1 Status (1)

This display is shown when the power is switched on, and it appears if the buttons of the control panel remain untouched for 15 minutes.



Status

Description

No settings can be made in this menu.

The actual value (process value, PV) of the control parameter, usually the outlet pressure, is shown in the upper right corner (G) together with the selected setpoint (SP) (H).

The upper half of the display (A) shows a graphic illustration of the system. The selected measuring parameters are shown with sensor symbol and actual value.

In MPC-E systems where the differential pressure across the pumps and pump curve data are known, the display shows the estimated flow rate when the flow rate and speed of the pumps are within a range where it is possible to estimate the flow rate.

≈ : This indicates that the flow rate is an estimated value.

The estimated flow rate may differ from a measured value.

In the middle of the display, an information field (I) is shown if any of the following events occurs:

- Limited operation due to standby pump
- Proportional-pressure influence active
- External setpoint influence active
- Alternative setpoint active
- Low flow boost active
- Pressure relief active
- Clock program active
- Remote-controlled via GENI (RS-485)
- Limited due to reduced operation
- Stopped due to low flow.

The lower display half (B) shows the following:

• the most recent active alarm, if any, and the fault cause with the fault code in brackets

- system status with actual operating mode and control source
- · pump status with actual operating mode.



If a fault has occurred, the warning symbol \triangle or alarm symbol \otimes is shown in the line (C) together with the cause and fault code, for instance "Overtemperature (64)".

If the fault is related to one of the pumps, one of the symbols \triangle or \otimes is also shown in front of the status line (D) of the pump in question. At the same time, the pump status indicator (E) changes colour to either yellow or red as described in the table below. The symbol \triangle or \otimes is shown to the right in the top line of the display (F). As long as a fault is present, this symbol is shown in the top line of all displays.

To open a menu line, select the line with [v] or $[\Lambda]$ and press [OK]. The display allows you to open status displays showing the following:

- actual alarms
- system status
- status of each pump.

Description of pump status

Pump status indicator	Description
Rotating, green	The pump is running.
Permanently green	The pump is ready (not running).
Rotating, yellow	Warning. The pump is running.
Permanently yellow	Warning. The pump is ready (not running).
Permanently red	Alarm. The pump is stopped.

5.2.2 Alarm log (3.2)

The alarm log can store up to 24 warnings and alarms.



Alarm log

Description

The display shows warnings and alarms.

- For every warning or alarm, the following is shown:
- Whether it is a warning \triangle or an alarm \otimes .
- Where the fault occurred: System, Pump 1, Pump 2, etc.
- In case of input-related faults, the input is shown.
- The cause of the fault and the alarm code in brackets, such as "Water shortage (214)".
- When the fault occurred: Date and time.
- When the fault disappeared: **Date and time**. If the fault still exists, date and time are shown as "--...-".

The most recent warning or alarm is shown at the top of the display.

5.2.3 Passwords

Passwords can be set to prevent unauthorised change of settings in the menus **Operation** and **Settings**.

See the Hydro MPC installation and operating instructions.

Both passwords are disabled. If a password is enabled, the factory setting is $\ensuremath{\textbf{1234}}.$

5.2.4 Alarm list

Check all active alarm codes before starting the fault correction.

Service passwords

If a customer password is set and not available for a Grundfos service engineer, the system can be unlocked by using the Grundfos service code **6814**. Protect this code and avoid unauthorised use of the code.

MPC alarm indication	Alarm	Associated	Decembration /	Demo de	Reset	Alarm/warning	
Protocol description	code	device and device number	Description/cause	Remedy	type ¹⁴⁾	Action type ¹⁵⁾	
Phase failure, pump	2	Pump 1-6	-	Check that all three mains phases are within a 15 V band.	Auto	Warning	
Too many restarts	7	Pump 1-6	HSD = hardware shut- down. There has been a fault, and the permissible number of restarts for the fault type has been exceeded. Fault in mains supply.	Restore mains supply. Replace terminal box.	Auto	Warning	
			Terminal box defective.				
Undervoltage, pump	40	Pump 1-6	Mains voltage is too low at start.	Bring voltage back to prescribed level.	Auto	Warning	
Undervoltage, pump	42	Pump 1-6	Faulty mains supply at the time of cutting in the terminal box.	Restore correct mains supply.	Auto	Warning	
Undervoltage, pump	73	Pump 1-6	Fall in mains supply. Mains supply failure while motor is running.	Restore correct mains supply.	Auto	Warning	
Overvoltage, pump	32	Pump 1-6	Mains voltage is too high at start.	Bring voltage back to prescribed level.	Auto	Warning	
Overload, associated device	48	Pump 1-6	Heavy overload has caused software shut- down (SSD).	Check and possibly reduce the load.	Auto	Warning	
Overload, associated device	50	Pump 1-6	MPF = motor protection function. The built-in motor protection has detected a sustained overload (MPF 60 sec. limit).	Check and possibly reduce load or improve cooling.	Auto	Warning	
Overload, associated device	51	Pump 1-6	Heavy overload (I _{max.} very high). Pump blocked at start.	Deblock the pump.	Auto	Warning	
Overload, associated device	54	Pump 1-6	The built-in motor protection has detected a transitory overload (MPF 3 sec. limit).	Check and possibly reduce load or improve cooling.	Auto	Warning	
Too high motor temperature	65, 70	Pump 1-6	PTC sensor in the motor has signalled overtemperature.	Check and possibly reduce load or improve cooling.	Auto	Warning	
Too high motor temperature	67	Pump 1-6	The terminal box has indicated overtemperature.	Check and possibly reduce load or improve cooling. Temperature during operation can be read via PC Tool E-products.	Auto	Warning	
Other fault, associated device	Try to re Switch o fault, associated 76 Pump 1-6 fault has occurred in the Switch o pump. If this do fault, rep		Try to reset the fault: Switch off the power supply. Wait until all diodes are out. Switch on the power supply. If this does not remedy the fault, replace the terminal box.	Auto	Warning		

MPC alarm indication	Alarm	Associated	Description	Demedu	Reset	Alarm/warning										
Protocol description	code	device and device number	Description/cause	Remedy	type ¹⁴⁾	Action type ¹⁵⁾										
Limit 1 exceeded	190	Measured	The measured parameter	Remove the cause of the	Man/	Alarm/warning										
		parameter	has exceeded the limit set.	fault.	auto	Stop/unchanged										
Limit 2 exceeded	191	Measured	The measured parameter	Remove the cause of the	Man/	Alarm/warning										
		parameter	has exceeded the limit set.	fault.	auto	Stop/unchanged										
Pressure relief	219	System	The monitored pressure could not be reduced sufficiently.	uld not be reduced Reduce the pressure to		Warning Unchanged										
			The pressure set cannot		Man/	Alarm/warning										
Pressure build-up fault	215	System	be reached within the configured time.	Check limit and pipes.	auto	Stop/unchanged										
Pumps outside duty			The pump is running		Man/	Warning										
range	208	System	outside the defined range.	Check the system.	auto	Unchanged										
Pilot pump fault	216	Pilot pump	Pilot pump fault.	Check wires. Check the pump.	Auto	Warning										
			The precharge pressure			Warning										
Water shortage Water shortage ¹⁶⁾	206		(or the level in the feed tank) is below its programmable warning limit.		Man/ auto	Unchanged										
		-	The precharge pressure	-		Alarm										
Water shortage	214		(or the level in the feed tank) is below its programmable alarm limit.	Check the actual pressure and the corresponding settings. Check the sensor/switch,	Man/ auto	Stop										
Water shortage ¹⁶⁾			The pressure switch			Warning										
			detects water shortage.	wiring and input according to the wiring diagram.		Unchanged										
Pressure high		_	The operating pressure is	Check the sensor/switch.		Alarm										
Pressure above maximum pressure ¹⁶⁾	210	210		above the programmable high-pressure alarm limit.		Man/ auto	Fast stop (overrules min. seq. time)									
Pressure low		Booster system The operating pressure is below the programmable low-pressure alarm limit.	Man/	Alarm/warning												
Pressure below min. pressure ¹⁶⁾	211						auto	Stop/unchanged								
Alarm, all pumps Alarm, all pumps ¹⁶⁾	203		All pumps set to Auto have stopped due to a pump alarm.	Fault-find according to the alarm message/code: System. Pumps installed. Use fault- finding for the pump.	Auto	Alarm										
														Pumps are not indicating alarm. Check the GENIbus wires, for instance connection and polarity.		Stop
		_		The fault reading can be		Alarm/warning										
External fault External fault ¹⁶⁾	003		The digital input set to External fault has been or is still closed.	reset with the Grundfos GO when the digital input is no longer closed. Reset by pressing [+] or [-].	Man/ auto	Stop/unchanged										
				Check the wiring and input		Warning										
Dissimilar sensor signals Dissimilar sensor signals ¹⁶⁾	204	Primary sensor and/or redundant sensor			Auto	Unchanged										
Fault, primary sensor Closed-loop feedback sensor signal fault ¹⁶⁾	089	Primary sensor	A fault in the sensor assigned to the feedback control has been detected.	Check the wiring and input according to the wiring diagram. Check the sensor output according to the value measured.	Auto	Alarm										
			Fault in the settings of the sensor assigned to the controller.	Check the settings of the primary sensor.		Stop										

MPC alarm indication	Alarm	Associated			Reset	Alarm/warning
Protocol description	code	device and device number	Description/cause	Remedy	type ¹⁴⁾	Action type ¹⁵⁾
		011.050	The signal, for instance 4	Check the wiring and input according to the wiring		Warning
Fault, sensor General (measurement) sensor signal fault ¹⁶⁾	088	CU 352 IO 351B as IO module	to 20 mA, from one of the analog sensors is outside the selected signal range.	diagram. Check the sensor output according to the value measured.	Auto	Unchanged
Internal fault, CU 352 Real-time clock out of order ¹⁶⁾	157		The real-time clock in the CU 352 is out of order.	Replace the CU 352.		VA/e me in e
Fault, Ethernet Ethernet: No address from DHCP server ¹⁶⁾	231	-	No address from DHCP server.	Communication fault.	-	Warning
Fault, Ethernet Ethernet: Auto-disabled due to misuse ¹⁶⁾	232	- CU 352	Auto-disabled due to misuse.	 Contact the system integrator. 	Auto	
FLASH parameter verification error FLASH parameter verification error ¹⁶⁾	083	-	Verification error in the CU 352 FLASH memory.	Replace the CU 352.		Unchanged
Other fault, associated device	83	-	Setting data not correct.	Other fault, associated device.		Warning
IO 351 internal fault			Hardware fault in the IO 351A.	See Actual alarms , and identify the faulty IO 351		Warning
Hardware fault, type 2 ¹⁶⁾	080	IO 351	Hardware fault in the IO 351B.	module from the alarm message. Replace the module.	Auto	Unchanged
		-	The VFD signal relay does	Check for VFD alarm.		Warning
VFD not ready VFD not ready ¹⁶⁾	213	Pump 1-6 CU 352	not release the VFD for operation.	Check the wiring and input according to the wiring diagram.	Auto	Unchanged
				See Actual alarms , and identify the faulty device from		Warning
Communication fault Pump communication fault ¹⁶⁾	010	Pump 1-6 IO 351	No GENIbus communication with a device connected to the CU 352.	the alarm message. Check the power supply. Check the GENIbus cable connection. Check that the GENIbus number of the device is correct, using the Grundfos	Auto	Unchanged
				GO. See Actual alarms and		Warning
	_			identify the faulty device from		6
Device alarms	From device	Pump 1-6	The device is in alarm condition.	the alarm message. Fault-find according to the service instructions for the device.	Auto	Unchanged

Auto acknowledgement (automatic).

14) Reset either of these types:

• Auto acknowledgement or Manual acknowledgement (automatic/manual).

15) System goes to operating mode **Stop** (no delay (< 0.5 s) between pump disconnections).

16) Protocol description.

5.3 Grundfos GO

The Grundfos GO can be used for setting the addresses of the IO 351 modules and for reading out settings. The general-purpose IO module inputs and outputs are set up via the CU 352 or with a PC Tool connected via the CU 352.

5.4 PC Tool E-products

The Grundfos PC Tool E-products supports the system and the components included. A detailed PC Tool Help assistant is available in the tool program, and a user manual in PDF format can be printed from the tool. The tool can be connected to the CU 352 of the system and communicate with IO modules and E-pumps. The **Network list** of the tool shows the units which are capable of communicating with the application in question. The tool supports these functions:

- network list
- monitor
- standard configuration
- custom configuration
- data logging
- updating configuration files.

5.4.1 Network list

This is a list of all GENIbus products connected to the network. Clicking **Network list** in the toolbar allows you to toggle between the network list expanded and collapsed.

5.4.2 Monitor

This function gives an overview and details of the operating status of the system.

Output

If the expected output function does not take place according to the graphical presentation, it may be due to the following faults:

- Defective component connected to the output. Check the component according to the wiring diagram.
- The output from the IO module does not function according to the graphical presentation. Check the physical output.

Input

If the expected input function does not take place according to the graphical presentation, it may be due to the following faults:

- The input signal is not as shown in the graphical presentation. Check that the signal is OK on the input terminal.
- The input of the IO module is defective. Replace the IO module.
- The CU 352 is defective.

5.4.3 Standard configuration

The standard configuration function allows you to select the appropriate standard configuration file for the system and send the file to the system.

It is possible to import a Grundfos Standard Configuration (GSC) file library via Tools > Update configuration files.

From factory, the system is configured/programmed for the application.

If an IO module is replaced, the new module will automatically be configured from the CU 352 when the system is restarted. Remember to give the new module the correct GENIbus address by means of the Grundfos GO.

If replaced, a CU 352 must be configured to the application in question. Follow the instructions in the **Help assistant**.

Standard configuration files are included in the tool when it is installed for the first time.

Subsequently, it is the user's responsibility to download the current version of the **Standard configuration file library**. See section Updating configuration files.

Related information

5.4.6 Updating configuration files

5.4.4 Custom configuration

The custom configuration function enables you to change selected standard configuration settings to a custom configuration. Custom configuration should be considered as an expert tool to be used for changing/adjusting standard data.

5.4.5 Data logging

Data logging of all data takes place continuously. In the network list, you can select the data to be visible. When the PC Tool is shut down, you will be asked whether you want to save your data log.

5.4.6 Updating configuration files

You can import an updated library of the standard configuration files from Tools > Update configuration files. You will get the option to choose the update method: browse for a zip-file or automatic (requires access to internet).

6. Configuration of Hydro MPC

6.1 Necessary equipment

- The following equipment is required:
- Grundfos GO
- PC Tool E-products.

Related information

- 6.2.1 Setting the GENIbus number in IO 351 modules, if any
- 6.2.2 Configuration of CU 352
- 6.2.3 Configuration of external frequency converters, if any
- 6.2.4 Step-by-step configuration of E-pumps, if any

6.2 Factory configuration of Hydro MPC

- To do the configuration, follow the below steps:
- 1. Set the GENIbus number in IO 351 modules, if any.
- 2. Configure CU 352.
- 3. Configure the external frequency converters, if any.
- 4. Configure the E-pump(s) step-by-step, if any.

6.2.1 Setting the GENIbus number in IO 351 modules, if any

Depending on the Control MPC system type and Control MPC options, the control panel is equipped with none or up to four IO 351A/B modules.

The modules present will have the designation numbers A1, A2, A01 or A03.

The units must have a GENIbus number according to the table below.

Module with designation	Address of module	Control MPC option GSC file to download
IO 351B interface	41	98272072
IO interface	42	98272073
Operating lights	41	98272076
Interface and operating lights	41 + 42	98272077
Pressure relief	41	98272079
Interface and pressure relief	41 + 42	98272081

To assign GENIbus numbers to the IO 351 module(s), if any, proceed as follows:

- 1. Switch on the power supply to the Control MPC.
- 2. Switch on the Grundfos GO with MI 301 and point it at the IR window of the first IO 351 to make contact with this module.



If there is more than one IO 351, move close to the IR window to make sure that only one module is communicating with the Grundfos GO at a time.



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⁻M054667

IR window of the IO 351

 For Grundfos GO, go to the Settings > NUMBER display. Set the address of the module according to the table above.



Grundfos GO

- 4. Send the number to the unit by pressing **OK** on the Grundfos GO.
- 5. Switch off Grundfos GO.
- 6. Repeat steps 2 to 4 for each IO 351 module.

6.2.2 Configuration of CU 352

To make the system work properly, CU 352 in the Control MPC must be configured with a number of GSC (Grundfos Standard Configuration) files.

- Control MPC requires a Control MPC GSC file which includes information about the system type in question (E, ES, ED, etc.) and the number of main pumps in the system.
- Control MPC based on one or two IO 351B modules with the designation numbers A01 and A03 requires a Control MPC options - GSC file.
- Hydro MPC requires a Hydro MPC GSC file describing the outlet pressure, sensor range and dry-running protection type.
- Hydro MPC fitted with a redundant primary sensor requires a Hydro MPC options GSC file.
- Hydro MPC requires a **Pump data GSC file** describing the performance curve of the pump in question. If a pilot pump is connected, a file describing the performance curve of the pilot pump in question must be loaded.

Note the right order of configuration:

- 1. Control MPC
- 2. Control MPC options
- 3. Hydro MPC
- 4. Hydro MPC options
- 5. Pump data
- 6. Pilot pump data, if any
- 7. Service contact information, if any.

Configuration of Control MPC

Example: Hydro MPC-ES with three pumps CRIE 5-8. Control MPC has two options, "Interface I/O module" and "Operating lights module".

Hydro MPC has one option, "Redundant sensor, 16 bar". The printed label of GSC files will look like this:

1	1. Control MPC	3. Hydro	MPC —		3	
2—	2. C-MPC options	4. H-MPC	options	5. Pump data —	5	
					4	
						072
	CONFIGURATION STEPS -PLE/		5 NUMBERS	96586126		TA021

Example of a printed label of GSC files

Pos.	Description
1	96307032
2	96592488
3	96307209
4	96592497
5	96307221



After the last GSC file download (if no further configurations are to be made), restart CU 352 by clicking **Restart** in the right bottom of the PC Tool.

When you click **Restart**, CU 352 will initialise. This procedure takes about 25 seconds.

Step-by-step configuration of Control MPC:

1. Set all automatic circuit breakers covering the pumps to off.

2. Connect the PC Tool to the service connection (TTL port) or USB connection on CU 352.



Service connection (TTL)



USB connection

- 3. Switch on the power supply to the Control MPC.
- 4. Start the PC Tool E-products.
- When communication has been established, the PC Tool Network list will display the icons for CU 352 and the IO 351 module(s), if any.
- 6. Select CU 352 in the Network list.
- 7. Select the PC Tool function Standard configuration. [F6].
- 8. Select Application in Search by.



9. Click the required application.

Search by	dard configuratio	on	
Number	1. Control MPC Number of pumps	2 pumps	
Application	System type	ES - All - E EF	
My Files		ES F S	
			.
		Sgarch Now	TM054441

- 10. From the drop-down menus, select the configuration of the current application.
- 11. When the selection has been made, click **Search Now** and the configuration file will appear.

Configuration No.	Number of pumps	System type	Description	Modified	
96307031	2 pumps	ES	SW.MPC.Control/ES/2/No/No	2008-04-02 11:58	
and t					
Found: 1					
			Compare	Restart Send	

12. A configuration file is now available as a result of the previous selections. In the **Configuration files** field, details on the configuration files can be found. Make sure that these details are correct and apply to the system.

13. Select the file from the Configuration files field and click Send.

🛞 Stand	lard configura	ation			
Search by	Number search				
Number	Configuration No.				
Application	1. Control MPC	3. Hydro MPC			
My Files	2. C-MPC Options	4. H-MPC Options	5. Pump Data		
	CONFIGURATION STEPS - PLE	ASE FOLLOW THE NUMBERS	96586126		TM054466
	Send configuratio	n file with original numbers	on product label.	Search Now	TMOF

- 14. Select Number in Search by.
- 15. Check that the selected configuration file number is now shown in the label under **1. Control MPC**. This indicates that CU 352 has received and stored the GSC file.

Follow the procedure described above to find and send the configuration files for the remaining applications:

- Control MPC options
- Hydro MPC

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- Hydro MPC options
- Pump data
- Pilot pump data, if available
- Service contact information, if available.

If no further configurations are to be made, restart CU 352 by clicking **Restart** in the right bottom of the PC Tool.

6.2.3 Configuration of external frequency converters, if any

The manufacturer's factory settings of the external frequency converter(s) used in Hydro MPC F, EF and EDF must be changed to the Grundfos settings before the system is ready for test.

To configure the external frequency converter:

- 1. Switch on the power supply to the frequency converter(s) by means of the automatic circuit breaker.
- 2. For each frequency converter, make the settings as described in the table below.

VLT 2800

Press QUICK MENU and + to access all parameters.

	Factory	/ setting		Gru	Indfos setting		
Parameter	Value or number in display of VLT			Function	Value or number in display of VLT		
	Function	Value	Number of function	- Function	Value	Number of function	
001	Language	English	[0]	Language	_ 17)	-	
101	Torque characteristic	Constant	[1]	Torque characteristic	Variable torque low	[2]	
101	Torque characteristic	torque	[1]	Torque characteristic	Variable torque medium	[3]	
102	Motor power	-	-	Motor power	_ 18)	-	
103	Motor voltage	230/400 V	-	Motor voltage	_ 18)	-	
104	Motor frequency	50 Hz		Motor frequency	_ 18)	-	
105	Motor current		-	Motor current	_ 18)	-	
106	Rated motor speed		-	Rated motor speed	_ 18)	-	
128	D Thermel meter protection	ormal mater protection No	[0]	Thermel meter protection	Thermistor trip, LC filter connected ¹⁹⁾	[2]	
120	Thermal motor protection	protection ¹⁹⁾	[0]	Thermal motor protection	No thermal protection, LC filter not connected ¹⁹	[0]	
136	Slip compensation	100 %	-	Slip compensation	0 %	-	
202	Output frequency high limit	132 Hz	-	Output frequency high limit	_20)	-	
205	Maximum reference	50 Hz	-	Maximum reference	_20)	-	
207	Ramp-up time 1	3 sec.	-	Ramp-up time 1	1 sec.	-	
208	Ramp-down time 1	3 sec.	-	Ramp-down time 1	1 sec.	-	
303	Digital input 10	Doversing	[0]	Digital input 10	Thermistor, LC filter connected ¹⁹⁾	[25]	
303	Digital input 19	Reversing	[9]	Digital input 19	No function, LC filter not connected ¹⁹⁾	[0]	
405	Reset function	Manual reset	[0]	Reset function	Auto reset x 10	[10]	
412	Variable switching	Without LC	[2]	Variable switching frequency	LC filter connected	[3]	
412	frequency	filter	[4]	variable switching requercy	Without LC filter	[2]	

17) For information about languages available, see relevant documentation.

¹⁸⁾ Use data from the system.

¹⁹⁾ Thermistor function used for thermal protection of LC filter.

 $^{20)}\,$ 51 Hz for a 50 Hz supply and 61 Hz for a 60 Hz supply.

Factory settings of VLT 2800

To recall the factory settings of all parameters, follow the procedure below:

1. Disconnect the power supply.

- 2. Press and hold QUICK MENU, + and CHANGE DATA and reconnect the power supply.
- 3. All parameters are now reset to the factory setting, except the fault log.

Press EXTEND MENU to access all parameters.

	Factory set	ting		Grundfos setting		
Parameter	Function		or number in lay of VLT	- Function	Value or number in display of VLT	
	Function	Value	Number of function	- Function	Value	Number of function
001	Language	-	-	Language	_21)	-
102	Motor power	-	-	Motor power	_22)	-
103	Motor voltage	-	-	Motor voltage	_22)	-
104	Frequency	50 Hz		Frequency	_22)	-
105	Motor current	-	-	Motor current	_22)	-
106	Rated motor speed	-	-	Rated motor speed	_22)	-
				Thermistor trip, LC filter connected ²³⁾	-	2
117	117 ETR trip1	-	4	No thermal protection, LC filter not connected ²³⁾	-	0
202	Maximum frequency	50 Hz	-	Maximum frequency	_24)	-
205	Maximum reference frequency	50 Hz	-	Maximum reference frequency	_24)	-
206	Ramp-up time	-	-	Ramp-up time	1 sec.	-
207	Ramp-down time	-	-	Ramp-down time	1 sec.	-
303	Reverse	-	1	No function	-	0
323	Alarm	-	8	Ready	-	1
400	Manual reset	-	0	Auto reset x 10	-	6
408	ASFM, adjustable switching	_	0	LC filter connected	-	2
400	frequency modulation	-	0	LC filter not connected	-	0

21) For information about languages available, see relevant documentation.

22) Use data from the system.

 $^{\rm 23)}\,$ Thermistor function used for thermal protection of LC/RFI filter.

 $^{24)}\,$ 51 Hz for a 50 Hz supply and 61 Hz for a 60 Hz supply.

Factory settings of VLT 6000

To recall the factory settings of all parameters, follow one of the procedures below:

Procedure 1

- 1. Set parameter 620 to (3).
- 2. Disconnect the power supply.
- 3. Reconnect the power supply.
- 4. All parameters are now reset to the factory setting, except the fault log.

Procedure 2

- 1. Disconnect the power supply.
- 2. Press and hold DISPLAY MODE, CHANGE DATA and OK and reconnect the power supply.
- 3. All parameters are now reset to the factory setting, except the fault log.

VLT FC 100 Press EXTEND MENU to access all parameters.

Parameter	Factor	y setting		Grundfos setting			
	Function	Value or number in display of VLT		Franction	Value or number in display of VLT		
	Function	Value Number of function		- Function	Value	Number of function	
001	Language	English	[0]	Language	_25)	-	
002	Motor speed unit	RPM	[0]	Motor speed unit	Hz	[1]	
120	Motor power	-	-	Motor power	_26)	-	
122	Motor voltage	-	-	Motor voltage	_26)	-	
123	Motor frequency	50 Hz	-	Motor frequency	_26)	-	
124	Motor current	_	-	Motor current	_26)	-	
125	Rated motor speed	1460 RPM	-	Rated motor speed	_26)	-	
100	Motor thermal protection	ETR trip 1	[4]	Thermistor trip, LC filter connected ²⁷⁾	Thermistor trip	[2]	
190				No thermal protection, LC filter not connected ²⁷⁾	No protection	[0]	
419	Maximum output frequency	100 Hz		Maximum output frequency	51 Hz	-	
303	Maximum reference	50 Hz		Maximum reference	_ 28)	-	
341	Ramp 1 ramp-up time	-	-	Ramp 1 ramp-up time	1 sec.	-	
342	Ramp 1 ramp-down time	-	-	Ramp 1 ramp-down time	1 sec.	-	
511	Digital input 19	Reversing	[10]	No operation	-	[0]	
540	Relay 1	Alarm	[9]	Relay 1	Drive ready	[2]	
540	Relay 2	Running	[5]	Relay 2	Control ready	[1]	
1420	Reset mode	Manual reset	[0]	Auto reset x 10	-	[10]	
1401	Switching frequency	4.0 Hz	[6]	Switching frequency	5.0 Hz	[7]	
		7.0112	[0]		-		

25) For information about languages available, see relevant documentation.

²⁶⁾ Use data from the system.

 $^{27)}\,$ Thermistor function used for thermal protection of LC/RFI filter.

²⁸⁾ 51 Hz for a 50 Hz supply and 61 Hz for a 60 Hz supply.

Factory setting of VLT FC 100

To recall the factory settings of all parameters, follow one of the procedures below:

Procedure 1

- 1. Set parameter 14-22.
- 2. Press OK.
- 3. Select Initialisation (for NLCP select 2).
- 4. Press OK.
- 5. Disconnect the power supply.
- 6. Reconnect the power supply.
- 7. All parameters are now reset to the factory setting, expect RFI 1, protocol, address, baud rate, minimum response delay, maximum inter.char delay, operating data, historic log and fault log.

Procedure 2

- 1. Disconnect the power supply.
- 2. Press and hold STATUS, MAIN MENU and OK and reconnect the power supply.
- 3. All parameters are now reset to the factory setting, expect the number of operating hours, power-ons and overtemperature and overvoltage faults.

6.2.4 Step-by-step configuration of E-pumps, if any

Before the system is ready for test, the E-pumps have to be set.

- 1. Switch on the power supply to the E-pumps by means of the automatic circuit breaker.
- Set the GENIbus number to the same number as that of the pump using Grundfos GO.

(Number = 1 for pump No 1, etc. Pilot pumps are set to GENIbus number 10.)

Pumps are numbered from left to right.



Pumps numbered from left to right

Pos.	Description
1	Pump 1
2	Pump 2

After the GSC file is downloaded, the configuration of each pump must be done by either PC Tool E-products (model C, D, F, G) or PC Tool Go Link (model H, I, J, K).

- 1. Connect the PC Tool to the pump you want to configure.
- 2. Select the PC Tool function **Standard configuration**.
- 3. Go to section Search by and select Number.
- 4. Find the relevant GSC file number from the table below.
- 5. Enter the GSC file number in the **Configuration No** field and click **Search Now**.
- 6. Select the file from the field Configuration files and click Send.
- 7. Repeat the steps for each E-pump.

GSC file number

Application	GSC file number
MGE 1-ph HM2MKII (model C)	95139670
MGE 3-ph HM3MKII (model D)	95139671
MGE 3-ph HMLarge (model F)	95139672
MGE 3-ph HM3MK11 (model G)	97913788
MGE 3-ph/1-ph (model H, I, J) ²⁹⁾	98428069
MGE 3-ph/1-ph (Model H, I, J) ³⁰⁾	98428068
MGE 3-ph (model H, I, J, K with FM 310) ²⁹⁾	93028557
MGE 3-ph (model H, I, J, K with FM 310) ³¹⁾	93145316

29) For MPC-E 3600 rpm & MPC-ED/ES 60 Hz.

30) For MPC-E 3000 rpm & MPC-ED/ES 50 Hz.

31) For MPC-E 3000 rpm & MPC-ED/ES 60 Hz.

Exchanging motors or pumps in existing systems

In service-related cases where there is a need to exchange either a motor or a complete pump, make sure that the pumps perform as equally as possible as they run synchronously.

If not compensated, in the worst case, the pump with the lowest pressure can heat up as it cannot overcome the system pressure and might be damaged.

Example: the original system is equipped with CRE 90-1, the system operates with a setpoint equal to the pump's nominal duty point. See below image.



As CRE 90-1 is discontinued, the replacement pump will be CRE 95-1. This pump has a better performance and can achieve the same performance as CRE 90-1 when operating at 95 % speed.



In this case, the maximum speed of the new pump must be set to 95~% speed.

Exchange from model F to model K

The model F motor is discontinued and can be exchanged with the permanent magnet motor model K. Implementation of the new motor does not have any impact in the production or in systems where all the motor types are the same. In service-related cases where we use both model F and model K, additional GSC files must be downloaded to introduce a "false" slip.

The model F motors run with a slip, as they are asynchronous motors. (Slip is the difference between the synchronous speed and asynchronous speed of an electrical induction motor). The model K, in combination with CRE, runs without slip by default, so the maximum speed is slightly higher on model K compared to model F, thereby achieving a better performance.



Example

TM057275

Pos.	Description
1	CRE 32-7, 22 kW, model K
2	CRE 32-7, 22 kW, model F
3	CRE 32-7-2, 22 kW, model K
4	CRE 32-7-2, 22 kW, model F
5	CRE 32-6, 18.5 kW, model K
6	CRE 32-6, 18.5 kW, model F

Exchange from model H, I, J with FM 300 to model H, I, J with FM 310

Type: MGE71A 4-FT85-IA	P.C.: 1223	INPUT	OUTPUT	Variant	
		U in:		PB: 311	
DE: 6204.2Z.C3			n: 1450-2000 rpm	FM: 310	TE5 Made in Hungary _ 🗸
	PF: 0.58-0.52 CL: F		PDS Eff 400%: 84.5%	HMI: 300	
Wgt: 10 kg E.P.	Tamb: 50 °C	11/1: 0.85-0.70 A		CIM: -	ES2 DE-BESD Bjerringbro Denmark

When the first models H, I, J permanent magnet motors are released (with FM 300), they are implemented with a "false" slip to be able to compare and mix with standard asynchronous motors. With the upgrade of model H, I, J to functional module FM 310, (with Bluetooth connectivity and Safe Torque Off (STO)), the CR small and medium range extends the maximum speed to 4000 rpm without slip, the CR large range continues with 3600 rpm, but now without slip.

The systems with CU 352 though continues with 3600 rpm on CR small and medium with slip (no change, use the standard GSC files). The CR large standard range also continues with 3600 rpm, but now without slip. Again, this does not have any impact if the system has the same motor type on all pumps, but in service-related cases with mixed motor versions, we have the same challenge as described with model F and K.

Remedy:

To avoid the difference in performance with mixed motor models on CR large (3600 rpm), an additional GSC file must be downloaded to the new model motor. This introduces a false slip so the new model motor can perform like a motor with slip (model F and H, I, J with FM 300).

The file depends on the kW size of the motor.

After exchanging a motor or a complete pump, use the Go Link PC-Tool to download the different GSC files, starting with:

- the correct pump GSC file (if only the motor is exchanged, it is already in a complete pump)
- 2. the MPC GSC file in above section
- 3. the "slip" file according to the table below.

Application	GSC file number
MGE 3-ph (model H, I, J, K) include slip 15 kW	93028570
MGE 3-ph (model H, I, J, K) include slip 18.5 kW	93028573
MGE 3-ph (model H, I, J, K) include slip 22 kW	93028578
MGE 3-ph (model H, I, J, K) include slip 11 kW	93145288
MGE 3-ph (model H, I, J, K) include slip 7.5 kW	93145289
MGE 3-ph (model H, I, J, K) include slip 5.5 kW	93145310
MGE 3-ph (model H, I, J, K) include slip 4 kW	93145311
MGE 3-ph (model H, I, J, K) include slip 3 kW	93145312
MGE 3-ph (model H, I, J, K) include slip 2.2 kW	93145313
MGE 3-ph (model H, I, J, K) include slip 1.1 kW	93145314
MGE 3-ph (model H, I, J, K) include slip 0.75 kW	93145315

The GSC file number is hidden, and you can only see the original pump GSC file when you connect the pump to the PC Tool.



- The firmware version for CU 352 must be V05.03.00 or newer to recognise model K.
- The correct GENI address can be set with either Go Link or Grundfos GO.

Configuration of the CUE, if any

The manufacturer's factory settings of the CUE used in Control MPC must be changed to the Control MPC settings before it is ready to test.

To configure the CUE:

- 1. Switch off the power supply to the CUE by means of the automatic circuit breaker.
- 2. Connect the PC Tool to the GENIbus terminals of the CUE which you want to configure.
- 3. Switch on the power supply to the CUE.
- 4. Start the PC Tool E-products.

- 5. When communication is established, the PC Tool **Network list** displays the icon for the CUE.
- 6. Select the CUE in the Network list.
- 7. Select the PC Tool function Custom configuration.
- Go to section **GENIbus**, and set the unit number to the same number as that of the CUE. (Number = 1 for CUE No 1, etc. Pilot pumps are set to 10.)

Steps 7 and 8 are not necessary for the CUE in Hydro MPC-F.

9. Go to section **General**, select **Pump Family** and enter motor data. See figure Terminal groups in section IO 351A.



Custom configuration

	Display language	English UK		-
eneral	Unit system	SI: m, kW,	bar	•
Alarm	Pump Family	CR, CRI, C	CRN, CRT	•
AGE IN				
nverter	Motor Nominal power	2200	W	
/Output	Nominal voltage	400	v	
	Nominal current	2.60	A	
inctions	Nominal frequency	50	Hz	
ENI bus	Nominal speed	2900	rpm	
etpoint				

TM054467

Custom configuration (general)

10. Select the PC Tool function **Standard configuration**.

- 11. Go to section Search by and select Number.
- 12. Enter the GCS file number according to below table in the **Configuration No.** field and click **Search Now**.

Application	Frequency	GSC file number
CUE-MPC/TOP/50 Hz	50 Hz (3000 rpm)	96890456
CUE-MPC/TOP/60 Hz	60 Hz (3600 rpm)	96890457
CUE-MPC/TOP/60 Hz - US	60 Hz (3600 rpm)	97685157

13. Select the file from the Configuration files field and click Send.

14. Switch on the power supply to the next CUE with the main switch and repeat steps 6 to 13 for each CUE.

Related information

4.2.1 IO 351A

7. Danfoss frequency converters

For further documentation on Danfoss frequency converters, see the manual supplied with the frequency converter, or download it from *http://www.danfoss.com*.

8. CUE

Service instructions, see Grundfos Product Center. Service instructions, extended, see GTI.

9. MGE

Service instructions, see Grundfos Product Center. Service instructions, extended, see GTI.

10. Disposal

10.1 Precautions for disposal

DANGER

Electric shock



Death or serious personal injury

 Before you dismantle the system, make sure that the power supply is disconnected and cannot be accidentally switch on.

Before you lift, make sure that the lifting equipment is capable of lifting this load, which is listed on the nameplate and on the packaging label.

WARNING Crushing of feet

Death or serious personal injury

WARNING

Hot surface

Death or serious personal injury

- Before you dismantle the system, make sure that the system is cooled down.



CAUTION Overhead load

Minor or moderate personal injury

- Use safety equipment when dismantling the system.



CAUTION Sharp element

Minor or moderate personal injury

Wear safety gloves.

10.2 Disposing of the system

This system or parts of it must be disposed of in an environmentally sound way:

- 1. Use the public or private waste collection service.
- 2. If this is not possible, contact the nearest Grundfos company or service workshop.

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